
Learning of Graphical Models – Parameter Estimation and Structure Learning

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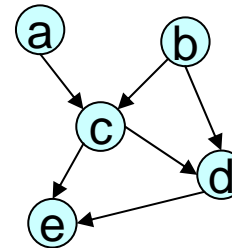
The Institute of Statistical Mathematics

Computational Methodology in Statistical
Inference II

Work with Graphical Models

■ Determining structure

- Structure given by modeling
e.g. Mixture model, HMM
- Structure learning



structure

→ Part IV

■ Parameter estimation

- Parameter given by some knowledge
- Parameter estimation with data
such as MLE or Bayesian estimation
→ Part IV

$$p(X_c | X_a)$$

$X_c \setminus X_a$	1	2	3
1	0.2	0.3	0.4
2	0.8	0.7	0.6

parameter

■ Inference

- Computation of posterior and marginal probabilities
(Already seen in Part III.)

Parameter Estimation

Statistical Estimation

■ Estimation from data

Statistical model with a parameter: $p(X | \theta)$ θ : parameter

I.i.d. Data: $D = (X_1, X_2, \dots, X_N)$

□ Maximum likelihood estimation

$$\hat{\theta} = \arg \max_{\theta} L(\theta),$$

$$L(\theta) = \prod_{i=1}^N p(X_i | \theta)$$

Likelihood function

or

$$\hat{\theta} = \arg \max_{\theta} \ell(\theta)$$

$$\ell(\theta) = \log L(\theta) = \sum_{i=1}^N \log p(X_i | \theta)$$

Log likelihood function

Statistical Estimation

- Bayesian estimation

- Distribution of the parameter θ is estimated

Prior probability $p(\theta)$ \rightarrow posterior probability $p(\theta | D)$

Bayes rule gives

$$p(\theta | D) = \frac{p(D | \theta)p(\theta)}{p(D)} = \frac{\prod_{i=1}^N p(X_i | \theta)p(\theta)}{\int \prod_{i=1}^N p(X_i | \theta)p(\theta)d\theta}$$

- Maximum a posteriori (MAP) estimation

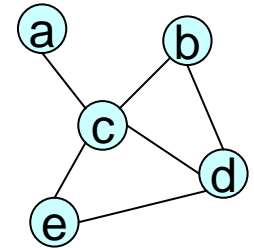
$$\hat{\theta}_{MAP} = \arg \max_{\theta} p(\theta | D)$$

Contingency Table

- ML estimation for discrete variables

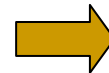
$$X_a \in \{1, \dots, M\} \quad X_b \in \{1, \dots, L\}$$

$$D = (X_a^{(1)}, X_b^{(1)}), \dots, (X_a^{(N)}, X_b^{(N)}) \quad \text{i.i.d. sample}$$



$X_c \backslash X_a$	1	2	3
1	12	18	4
2	6	9	14

N_{ij} : Number of counts



$p(X_a, X_c)$

$X_c \backslash X_a$	1	2	3
1	p_{11}	p_{12}	p_{13}
2	p_{21}	p_{22}	p_{22}

Estimation of probabilities

ML estimator

$$\hat{p}_{ij} = \frac{N_{ij}}{N}$$

Bayesian Estimation: Discrete Case

- Bayesian estimation for discrete variables

Model: $p(X_a, X_b | \theta)$

$$p(X_a = i, X_b = j | \theta) = \theta_{ij}, \quad \theta = (\theta_{ij}) \in \Delta_{ML-1}$$

$$\Delta_{K-1} \equiv \{\theta \in \mathbf{R}^K \mid \theta_i \geq 0 (\forall i), \sum_{i=1}^K \theta_i = 1\}$$

Prior: $\pi(\theta)$ on Δ_{ML-1}

Likelihood: $p(D | \theta) = \prod_{n=1}^N p(X_a^{(n)}, X_b^{(n)} | \theta) = \prod_{i,j} \theta_{ij}^{N_{ij}}$ **Multinomial**

Bayesian estimation:

$$p(\theta | D) = \frac{p(D, \theta)}{p(D)} = \frac{p(D | \theta) \pi(\theta)}{\int_{\Delta} p(D | \theta) \pi(\theta) d\theta} = \frac{\prod_{i,j} \theta_{ij}^{N_{ij}} \pi(\theta)}{\int_{\Delta} \theta_{ij}^{N_{ij}} \pi(\theta) d\theta}$$

This integral is difficult to compute in general.

Dirichlet Distribution

■ Dirichlet distribution

- Density function of K -dimensional **Dirichlet distribution**

$$\text{Dir}(\theta \mid \alpha_1, \dots, \alpha_K) = \frac{\Gamma(\sum_{j=1}^K \alpha_j)}{\prod_{j=1}^K \Gamma(\alpha_j)} \prod_{j=1}^K \theta_j^{\alpha_j-1} \propto \prod_{j=1}^K \theta_j^{\alpha_j-1}$$

$$\text{on } \Delta_{K-1} = \{\theta \in \mathbb{R}^K \mid \theta_j \geq 0, \sum_{j=1}^K \theta_j = 1\}$$

where

$(\alpha_1, \dots, \alpha_K)$: parameter ($\alpha_j > 0$)

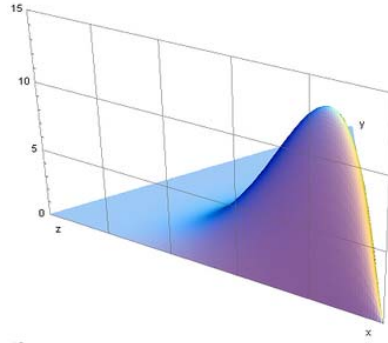
$\Gamma(\alpha)$: Gamma function $\Gamma(\alpha) = \int_0^\infty t^{\alpha-1} e^{-t} dt$

$\Gamma(\alpha) = (\alpha - 1)\Gamma(\alpha - 1)$ for $\alpha > 1$

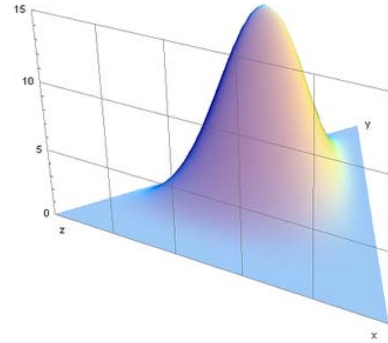
$\Gamma(n) = (n - 1)!$ for a positive integer n .

Dirichlet Distribution

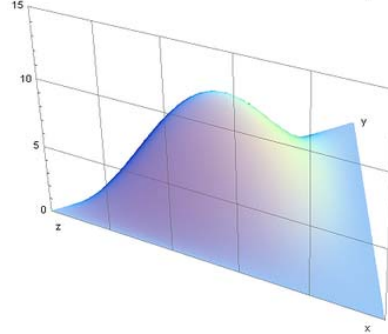
$$\alpha = (6, 2, 2)$$



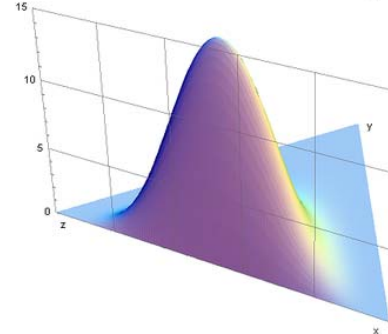
$$\alpha = (3, 7, 5)$$



$$\alpha = (2, 3, 4)$$



$$\alpha = (6, 2, 6)$$



□ Expectation

$$E[\theta_i] = \frac{\alpha_i}{\sum_{j=1}^K \alpha_j}$$

- The mean point is proportional to the vector α .
- The mean point is a stable point (i.e. differential = 0), and it may be either maximum or minimum.

Dirichlet Prior

- Dirichlet distribution works as a prior to multinomial distribution
Posterior is also Dirichlet -- conjugate prior

$$p(\theta | D) = \frac{\prod_k \theta_k^{N_k} \text{Dir}(\theta | \alpha)}{\int_{\Delta} \theta_k^{N_k} \text{Dir}(\theta | \alpha) d\theta} = \text{Dir}(\theta | \tilde{\alpha}) \quad \text{--- (*)}$$

$$\tilde{\alpha} = (N_1 + \alpha_1, \dots, N_K + \alpha_K)$$

α works as a prior count.

- MAP estimator

$$\hat{\theta}_{MAP} = \frac{\tilde{\alpha}_i}{\sum_{j=1}^K \tilde{\alpha}_j} = \frac{N_i + \alpha_i}{N + \alpha_1 + \dots + \alpha_K}$$

Proof of (*)

$$p(\theta | D) \propto \prod_{j=1}^K \theta_j^{N_j} \text{Dir}(\theta | \alpha) \propto \prod_{j=1}^K \theta_j^{N_j + \alpha_j - 1}$$

By the normalization, the right hand side must be $\text{Dir}(\theta | \tilde{\alpha})$.

EM Algorithm for Models with Hidden Variables

ML Estimation with Hidden Variable

- Statistical model with hidden variables

Suppose we can assume **hidden (unobservable) variables** in addition to observable variables

$$p(X, Z | \theta)$$

X : observable variable

Z : hidden variable

θ : parameter

We have data only for observable variables: $D = (X_1, X_2, \dots, X_N)$

The ML estimation must be done with X

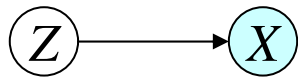
$$\sum_{n=1}^N \log p(X_n | \theta) = \sum_{n=1}^N \log \left(\sum_{Z_n} p(X_n, Z_n | \theta) \right)$$

But, this maximization is often difficult by nonlinearity w.r.t θ .

ML Estimation with Hidden Variable

- Example: Gaussian mixture model

With hidden variable: $p(X, Z | \theta) = p(Z | \pi) \phi(x | \mu_j, \Sigma_j)$



Z takes values in $\{1, \dots, K\}$: component

$$\theta = (\pi, \mu_1, \Sigma_1, \dots, \mu_K, \Sigma_K)$$

Marginal of X : $p(x | \theta) = \sum_{j=1}^K \pi_j \phi(x | \mu_j, \Sigma_j)$

- ML estimation

$$\max_{\theta} \sum_{n=1}^N \log p(X_n | \theta) = \max_{\theta} \sum_{n=1}^N \log \left(\sum_{j=1}^K \pi_j \phi(X_n | \mu_j, \Sigma_j) \right)$$

π_j and (μ_j, Σ_j) are coupled \rightarrow difficult to solve analytically.

Estimation with Complete Data

- Complete data

- Suppose Z_1, \dots, Z_N are **known**.

$$D_c = \{(X_1, Z_1), \dots, (X_N, Z_N)\} \quad : \text{complete data}$$

ML estimation with D_c is often easier than estimation with D .

$$\max \ell_c(D_c | \theta),$$

where

$$\ell_c(D_c | \theta) = \sum_{n=1}^N \log p(X_n, Z_n | \theta) \quad \text{Complete log likelihood}$$

Estimation with Complete Data

- Example: Mixture of Gaussian

Redefine the hidden variable Z by K dimensional binary vector:

$$p(X, Z | \theta) = \prod_{a=1}^K \{ \pi_a \phi(x | \mu_a, \Sigma_a) \}^{Z_a}$$

$Z = (Z_1, \dots, Z_K)$ takes values in

$\{ (1, 0, 0, \dots, 0), (0, 1, 0, \dots, 0), \dots, (0, 0, 0, \dots, 1) \}$ **K class**

Note:
$$p(X | \theta) = \sum_Z p(X, Z | \theta) = \sum_{a=1}^K \pi_a \phi(x | \mu_a, \Sigma_a)$$

Estimation with Complete Data

ML estimation with complete data:

$$\begin{aligned}\sum_{n=1}^N \log p(X_n, Z_n | \theta) &= \sum_{n=1}^N \log \left(\prod_{i=1}^K \{ \pi_i \phi(X_n | \mu_i, \Sigma_i) \}^{Z_i^n} \right) \\ &= \sum_{n=1}^N \sum_{i=1}^K Z_i^n \{ \log \pi_i + \log \phi(X_n | \mu_i, \Sigma_i) \}\end{aligned}$$

π_j and (μ_j, Σ_j) are decoupled \rightarrow they can be maximized separately.

$$\left\{ \begin{array}{l} \max_{\pi} \sum_{n=1}^N \sum_{i=1}^K Z_i^n \log \pi_i \quad \text{subj. to} \quad \sum_{i=1}^K \pi_i = 1 \\ \max_{\mu, \Sigma} \sum_{n=1}^N \sum_{i=1}^K Z_i^n \log \phi(X_n | \mu_i, \Sigma_i) \end{array} \right. \quad \begin{array}{l} \text{Maximization} \\ \text{is easy.} \end{array}$$

But, the complete data is **not available** in practice!

Expected Complete Log Likelihood

- Use **expected complete log likelihood** instead of complete log likelihood.
- Complete log likelihood

$$\ell_c(D_c | \theta) = \sum_{n=1}^N \log p(X_n, Z_n | \theta)$$

- Expected complete log likelihood
 - Suppose we have a **current guess** $\hat{\theta}^{(t)}$

Use expectation w.r.t. $p(Z_n | X_n, \hat{\theta}^{(t)})$

$$\langle \ell_c(D_c | \theta) \rangle_{\hat{\theta}^{(t)}} = \sum_{n=1}^N \sum_{Z_n} p(Z_n | X_n, \hat{\theta}^{(t)}) \log p(X_n, Z_n | \theta)$$

Maximize θ of $\langle \ell_c(D_c | \theta) \rangle_{\hat{\theta}^{(t)}}$

EM Algorithm

Initialization

Initialize $\theta = \theta^{(0)}$ by some method.

$t = 0$.

Repeat the following steps until stopping criterion is satisfied.

E-step

Compute the expected complete log likelihood $\langle \ell_c(D_c | \theta) \rangle_{\hat{\theta}^{(t)}}$

M-step

Maximize θ of $\langle \ell_c(D_c | \theta) \rangle_{\hat{\theta}^{(t)}}$

$$\hat{\theta}^{(t+1)} = \arg \max_{\theta} \langle \ell_c(D_c | \theta) \rangle_{\hat{\theta}^{(t)}}$$

- Computational difficulty of M-step depends on a model

EM Algorithm for Gaussian Mixture

- Complete log likelihood

$$\ell_c(D_c | \theta) = \sum_{n=1}^N \sum_{i=1}^K Z_i^n \{ \log \pi_i + \log \phi(X_n | \mu_i, \Sigma_i) \}$$

- Expected complete log likelihood

$$\begin{aligned} \tau_i^{n(t)} &= E[Z_i^n | X_n, \hat{\theta}^{(t)}] = p(Z_i^n = 1 | X_n, \hat{\theta}^{(t)}) = \frac{p(X_n, Z_i^n = 1 | \hat{\theta}^{(t)})}{p(X_n | \hat{\theta}^{(t)})} \\ &= \frac{\hat{\pi}_i^{(t)} \phi(X_n | \hat{\mu}_i^{(t)}, \hat{\Sigma}_i^{(t)})}{\sum_{j=1}^K \hat{\pi}_j^{(t)} \phi(X_n | \hat{\mu}_j^{(t)}, \hat{\Sigma}_j^{(t)})} \end{aligned}$$

Ratio of contribution of X_n to the i -th component.

- E-step

$$\langle \ell(D_c | \theta) \rangle_{\hat{\theta}^{(t)}} = \sum_{n=1}^N \sum_{i=1}^K \tau_i^{n(t)} \{ \log \pi_i + \log \phi(X_n | \mu_i, \Sigma_i) \}$$

EM Algorithm for Gaussian Mixture

□ M-step

$$\hat{\pi}_i^{(t+1)} = \frac{1}{N} \sum_{n=1}^N \tau_i^{n(t)}$$

$$\hat{\mu}_i^{(t+1)} = \frac{\sum_{n=1}^N \tau_i^{n(t)} X_n}{\sum_{n=1}^N \tau_i^{n(t)}} \quad \text{weighted mean}$$

$$\hat{\Sigma}_i^{(t+1)} = \frac{\sum_{n=1}^N \tau_i^{n(t)} (X_n - \hat{\mu}_i^{(t)})(X_n - \hat{\mu}_i^{(t)})^T}{\sum_{n=1}^N \tau_i^{n(t)}} \quad \text{weighted covariance matrix}$$

(Proof omitted. Exercise)

EM Algorithm for Gaussian Mixture

- Meaning of τ

Z_n^i : unobserved

		i			
		1	2	3	K
n	1	0	1	0	0
	2	0	0	0	1
	3	1	0	0	0
		\vdots			\vdots
	N	0	0	0	1

$$\tau_n^{i(t)} = E\left[Z_n^i \mid X_n, \hat{\theta}^{(t)}\right]$$

		i				
		1	2	3	K	SUM
n	1	0.1	0.7	0	0.2	→ 1
	2	0.2	0.1	0.2	0.5	→ 1
	3	0.8	0.1	0.05	0.05	→ 1
		\vdots			\vdots	\vdots
	N	0.13	0.11	0.06	0.7	→ 1

Properties of EM Algorithm

- EM converges quickly for many problems.
- Monotonic increase of likelihood of X is guaranteed (discussed later).
- EM may be trapped by local optima.
- The solution depends strongly on the initial state.
- EM algorithm can be applied to any model with hidden variables. Missing value, etc.

Demonstration

- Web site for Gaussian mixture demo:

<http://www.neurosci.aist.go.jp/~akaho/MixtureEM.html>

Theoretical Justification of EM

Theoretical Justification of EM

■ EM as likelihood maximization

The goal is to maximize the (incomplete) log likelihood, not the expected complete log likelihood.

$q(Z | X)$: arbitrary p.d.f. of Z , may depend on X .

Define an auxiliary function $L(q, \theta)$ by

$$L(q, \theta) = \sum_Z q(Z | X) \log \frac{p(X, Z | \theta)}{q(Z | X)}.$$

Theorem 1

E-step: $q^{(t+1)} = \arg \max_q L(q, \hat{\theta}^{(t)})$ (and compute $\langle \ell_c(D_c | \theta) \rangle_{q^{(t+1)}}$)

M-step: $\hat{\theta}^{(t+1)} = \arg \max_{\theta} L(q^{(t+1)}, \theta)$

Alternating optimization w.r.t. q and θ .

Theoretical Justification of EM

Proposition 1 (L and likelihood of X)

For any $q(Z | X)$ and θ , the log likelihood of X is decomposed as

$$\ell(X | \theta) = L(q, \theta) + KL(q(Z | X) || p(Z | X, \theta))$$

In particular,

$$\ell(X | \theta) \geq L(q, \theta) \quad \text{for all } q \text{ and } \theta,$$

and the equality holds if and only if $q = p(Z | X, \theta)$.

Proof) $\ell(\theta | X) - L(q, \theta)$

$$= \sum_Z q(Z | X) \log p(X | \theta) - \sum_Z q(Z | X) \log \frac{p(X, Z | \theta)}{q(Z | X)}$$

$$= \sum_Z q(Z | X) \log \frac{p(X | \theta) q(Z | X)}{p(X, Z | \theta)}$$

$$= \sum_Z q(Z | X) \log \frac{q(Z | X)}{p(Z | X, \theta)}$$

Theoretical Justification of EM

Proposition 2 (L and expected complete likelihood)

$$L(q, \theta) = \langle \ell_c(X, Z | \theta) \rangle_q - \sum_Z q(Z | X) \log q(Z | X)$$

proof)

$$\begin{aligned} \langle \ell(X, Z | \theta) \rangle_q &= \sum_Z q(Z | X) \log p(X, Z | \theta) \\ &= \sum_Z q(Z | X) \log \frac{p(X, Z | \theta) q(Z | X)}{q(Z | X)} \\ &= \sum_Z q(Z | X) \log \frac{p(X, Z | \theta)}{q(Z | X)} + \sum_Z q(Z | X) \log q(Z | X) \\ &= L(q, \theta) + \sum_Z q(Z | X) \log q(Z | X) \end{aligned}$$

Theoretical Justification of EM

■ Proof of Theorem 1

□ E-step:

From Proposition 1,

$$\underbrace{\ell(X | \hat{\theta}^{(t)})}_{\text{independent of } q} = \underbrace{L(q, \hat{\theta}^{(t)})}_{\text{maximize}} + \underbrace{KL(q(Z | X) \| p(Z | X, \hat{\theta}^{(t)}))}_{\text{minimize}}$$

independent of q maximize \Leftrightarrow minimize

$$\Rightarrow p(Z | X, \hat{\theta}^{(t)}) = \arg \max_q L(q, \hat{\theta}^{(t)})$$

□ M-step:

From Proposition 2,

$$L(q^{(t+1)}, \theta) = \langle \ell_c(X, Z | \theta) \rangle_{p(Z|X, \hat{\theta}^{(t)})} - (\text{const. w.r.t. } \theta)$$

M-step is

$$\max_{\theta} L(q^{(t+1)}, \theta)$$

Theoretical Justification of EM

- Monotonic increase of likelihood by EM

Theorem

$$\ell(X | \hat{\theta}^{(t)}) \leq \ell(X | \hat{\theta}^{(t+1)}) \quad \text{for all } t .$$

Proof)

$$\ell(X | \hat{\theta}^{(t)}) = L(q^{(t+1)}, \hat{\theta}^{(t)}) \quad (\text{E-step, Prop.1})$$

$$\leq L(q^{(t+1)}, \hat{\theta}^{(t+1)}) \quad (\text{M-step})$$

$$\leq \ell(X | \hat{\theta}^{(t+1)}) \quad (\text{Prop.1})$$

Remarks on EM Algorithm

- EM always increases the likelihood of observable variables, but there are no theoretical guarantees of global maximization. In general, it can converge only to a local maximum.
- There is a sufficient condition of convergence by Wu (1983).
- Practically, EM converges very quickly.

- For Gaussian mixture model,
 - If the mean and variance are its parameters, the likelihood function can take an arbitrary large value. There is no global maximum of likelihood.
 - EM often finds a reasonable local optimum by a good choice of initialization.
 - The results depend much on the initialization.

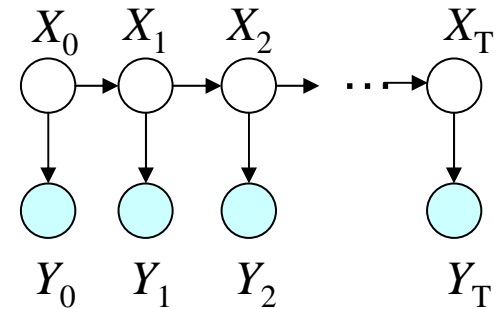
- Further readings:
 - *The EM Algorithm and Extensions* (McLachlan & Krishnan 1997)
 - *Finite Mixture Models* (McLachlan & Peel 2000)

EM Algorithm for Hidden Markov Model

Maximum Likelihood for HMM

■ Parametric model of Gaussian HMM

$$p(X, Y) = p(X_0) \prod_{t=0}^{T-1} p(X_{t+1} | X_t) \prod_{t=0}^T p(Y_t | X_t)$$



$$p(X_0 = j) = \pi_j \quad \text{initial probability}$$

$$p(X_{t+1} = j | X_t = i) = A_{ij} \quad \text{transition matrix}$$

$$p(Y_t | X_t = j) = \phi(y_t; \mu_j, \Sigma_j) \quad \text{Gaussian with mean } \mu_j \text{ and covariance } \Sigma_j$$

parameter: $\theta = (\pi, (A_{ij}), \mu_1, \dots, \mu_K, \Sigma_1, \dots, \Sigma_K)$

$$p(Y | \theta) = \sum_{X_0} \cdots \sum_{X_T} \pi_{X_0} \prod_{t=0}^{T-1} A_{X_{t+1} X_t} \prod_{t=0}^T \phi(y_t | \mu_{X_t}, \Sigma_{X_t})$$

max log $p(Y | \theta)$ is difficult.

EM for HMM

■ Complete likelihood

$$\ell_c(Y, X | \theta) = \log p(Y, X | \theta)$$

$$= \log \left(\pi_{X_0} \prod_{t=0}^{T-1} A_{X_t X_{t+1}} \prod_{t=0}^T \phi(Y_t | \mu_{X_t}, \Sigma_{X_t}) \right)$$

$$= \log \pi_{X_0} + \sum_{t=0}^{T-1} A_{X_t X_{t+1}} + \sum_{t=0}^T \left\{ -\frac{1}{2} (Y_t - \mu_{X_t})^T \Sigma_{X_t}^{-1} (Y_t - \mu_{X_t}) - \frac{1}{2} \log \det \Sigma_{X_t} - \frac{m}{2} \log(2\pi) \right\}$$

$$= \sum_{j=1}^K \delta_{jX_0} \log \pi_j + \sum_{i,j=1}^K \sum_{t=0}^{T-1} \delta_{jX_{t+1}} \delta_{iX_t} A_{ij}$$

$$+ \sum_{j=1}^K \sum_{t=0}^T \delta_{jX_t} \left\{ -\frac{1}{2} (Y_t - \mu_j)^T \Sigma_j^{-1} (Y_t - \mu_j) - \frac{1}{2} \log \det \Sigma_j - \frac{m}{2} \log(2\pi) \right\}$$

EM for HMM

■ Expected complete likelihood

Suppose we already have an estimate $\hat{\theta}^{(n)}$ (n : index for iteration)

$$\langle \ell_c(Y, X | \theta) \rangle_{\hat{\theta}^{(n)}} = \sum_X p(X | Y, \hat{\theta}^{(n)}) \log p(Y, X | \theta)$$

It requires

$$\langle \delta_{jX_t} \rangle_{\hat{\theta}^{(n)}} = \sum_{X_t=1}^K p(X_t | Y, \hat{\theta}^{(n)}) \delta_{jX_t} = p(X_t = j | Y, \hat{\theta}^{(n)}) \equiv \gamma_t^{j(n)}$$

$$\begin{aligned} \langle \delta_{iX_t} \delta_{jX_{t+1}} \rangle_{\hat{\theta}^{(n)}} &= \sum_{X_t=1}^K \sum_{X_{t+1}=1}^K p(X_t, X_{t+1} | Y, \hat{\theta}^{(n)}) \delta_{iX_t} \delta_{jX_{t+1}} \\ &= p(X_t = i, X_{t+1} = j | Y, \hat{\theta}^{(n)}) \equiv \xi_{t,t+1}^{i,j(n)} \end{aligned}$$

$$p(X_t = j | Y, \hat{\theta}^{(n)}) \text{ and } p(X_t = i, X_{t+1} = j | Y, \hat{\theta}^{(n)})$$

can be computed by the **forward-backward algorithm**.

EM for HMM – Baum-Welch Algorithm

■ E-step

- Forward-backward to compute $\gamma_t^{j(n)}$ and $\xi_{t,t+1}^{i,j(n)}$.
- Expected complete log likelihood

$$\begin{aligned} \langle \ell_c(Y, X | \theta) \rangle_{\hat{\theta}^{(n)}} &= \sum_{j=1}^K \gamma_0^{j(n)} \log \pi_j + \sum_{i,j=1}^K \sum_{t=0}^{T-1} \xi_{t,t+1}^{i,j(n)} A_{ij} \\ &+ \sum_{j=1}^K \sum_{t=0}^{T-1} \gamma_t^{j(n)} \left\{ -\frac{1}{2} (Y_t - \mu_j)^T \Sigma_j^{-1} (Y_t - \mu_j) - \frac{1}{2} \log \det \Sigma_j - \frac{m}{2} \log(2\pi) \right\} \end{aligned}$$

■ M-step

$$\begin{aligned} \hat{\pi}_j^{(n+1)} &= \gamma_0^{j(n)}, & \hat{A}_{i,j}^{(n+1)} &= \frac{\sum_{t=0}^{T-1} \xi_{t,t+1}^{i,j(n)}}{\sum_{k=1}^K \sum_{t=0}^{T-1} \xi_{t,t+1}^{i,k(n)}} = \frac{\sum_{t=0}^{T-1} \xi_{t,t+1}^{i,j(n)}}{\sum_{t=0}^{T-1} \gamma_t^{i(n)}} \\ \hat{\mu}_i^{(n+1)} &= \frac{\sum_{t=0}^{T-1} \gamma_t^{i(n)} Y_t}{\sum_{t=0}^{T-1} \gamma_t^{i(n)}}, & \hat{\Sigma}_i^{(n+1)} &= \frac{\sum_{t=0}^{T-1} \gamma_t^{i(n)} (Y_t - \mu_i^{(n+1)})(Y_t - \mu_i^{(n+1)})}{\sum_{t=0}^{T-1} \gamma_t^{i(n)}} \end{aligned}$$

Summary: Parameter learning

- Discrete variables without hidden variables
 - Maximum likelihood estimation is easy by frequencies.
 - Bayesian estimation is often done with Dirichlet prior.
- Discrete variables with hidden variables
 - Maximum likelihood estimation can be done with EM algorithm.
 - Bayesian approach → computational difficulty. variational method and so on.