

## Checking the adequacy of partial linear models with missing covariates at random

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**Abstract** In this paper, we consider the goodness-of-fit for checking whether the nonparametric function in a partial linear regression model with missing covariate at random is a parametric one or not. We estimate the selection probability by using parametric and nonparametric approaches. Two score type tests are constructed with the estimated selection probability. The asymptotic distributions of the test statistics are investigated under the null and local alternative hypothesis. Simulation studies are carried out to examine the finite sample performance of the sizes and powers of the tests. We apply the proposed procedure to a data set on the AIDS clinical trial group (ACTG 315) study.

**Keywords** Partial linear model · Lack-of-fit test · Covariates missing at random · Inverse probability weights

### 1 Introduction

To fix notation, let  $Y$  denote a continuous outcome variable,  $X$  and  $T$  be the exposure variables with  $p$  and  $q$ -dimensional vectors, respectively, the partial linear model can

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be written as

$$Y = X^\tau \beta + g(T) + \varepsilon, \quad (1)$$

where  $\beta$  is an unknown parameter vector of dimension  $p$ ,  $g(\cdot)$  is an unknown measurable function, and  $\varepsilon$  is the error term with  $E(\varepsilon|X, T) = 0$  and  $E(\varepsilon^2|X, T) = \sigma^2(X, T) < \infty$ . We use the superscript  $\tau$  in (1) denote a transpose. Here, we assume that the variable  $T$  is a scalar for simplicity. The proposed methods in this paper can be extended to the situation when  $T$  is a multivariate variable.

When the data set is completed, there are many literature investigating the goodness-of-test for a partial linear model. For checking whether the partial linear model in (1) is correct for data fitting, i.e.,  $H_0 : E(Y|X, T) = X^\tau \beta + g(T)$  for some  $\beta$  and  $g(\cdot)$ , among others, Whang and Andrews (1993) and Yatchew (1992) used sample splitting to recommend ad hoc methods to handle this problem. To avoid the use of ad hoc modification and improve the power performance, Fan and Li (1996), based on a kernel estimator of the conditional expectation of residuals given  $(X, T)$ , constructed a consistent test for the above  $H_0$ . To obtain some distribution-free test, Zhu and Ng (2003) proposed a residual marked process test. For the implementation of their procedure, they resorted to a variant of the wild bootstrap approximation called “Random Symmetrization”.

In practice, we are also concerned with the question whether the nonparametric part in (1) is a parametric function, that is,  $H_0 : g(\cdot) = g(\cdot, \theta)$  for some  $\theta$  and a known function  $g(\cdot, \theta)$ . If the null hypothesis for some known function  $g(\cdot, \theta)$  such as linear function holds, we can carry out more efficient statistical inference. On the other hand, if we misspecify the regression model, we are at the risk of getting biased estimator and unreliable inference. For this issue, among others, Li et al. (2011) proposed a test to check the linearity of the nonparametric portion by a linear interpolation and obtain the  $p$  value using the fiducial method. Liang (2006) developed a Crámer-von Mises statistic and likelihood ratio test for checking the linearity of nonparametric function. Li (2009) proposed two Wald-type spline-based test statistics to check the linearity of partially linear models.

It is quite common in practice that some covariates variable, denoted it as  $U$  with  $X = (U, V)$ , may be not available. Missing covariates data can arise due to various reasons such as limited budget to measure for the full study cohort, refusals to reply to certain question to supply the desired information, drop outs due to serious side effects, failure on the part of investigator to gather correct information, errors in the measuring apparatus, and so forth.

When the partial linear model is missing response at random, there are many investigations in the literature for the estimation of  $\beta$  and  $g(\cdot)$ , and goodness-of-fit problems. For estimation of the partial linear model, among others, Wang et al. (2004) defined a class of estimators including semiparametric regression imputation estimator, marginal average estimator and (marginal) propensity score weighted estimator for the marginal mean of response. Wang and Sun (2007) proposed imputation, semiparametric regression surrogate and inverse marginal probability weighted methods to estimate the parameters and nonparametric function, respectively. Liang et al. (2007) developed a class of semiparametric estimators for the partial linear model with miss-

ing response variables and error-prone covariates. For testing of the partial linear model, among others, Xu et al. (2012) constructed two completed data sets based on imputation and marginal inverse probability weighted methods, and developed two empirical process-based tests for checking whether the nonparametric part in (1) is a parametric function. Sun et al. (2009) proposed two empirical process-based tests for checking whether model (1) with missing response is plausible for data fitting.

When the covariates are missing, Liang et al. (2004) estimated the regression parameter by employing the augmented inverse weight probability method asbreak in Robins et al. (1994). Wang (2009) proposed a model calibration-based method and a weighted way to estimate the parameter and nonparametric function, respectively. To our knowledge, few works focus on the goodness-of-fit for the partial linear model with missing covariate data. Evidently, it is an interesting topic for testing whether the nonparametric function is a parametric form in model (1) with missing covariates, and the existing methods for complete data may not be used directly.

In this paper, for the model (1) with covariates missing at random, we consider testing

$$H_0 : g(\cdot) = g(\cdot, \theta) \quad (2)$$

for some  $\theta$  and known function  $g(\cdot, \theta)$ . Our test statistics are based on a weighted version of the residual. We choose the commonly used inverse selection probability as the weighted function, which is estimated parametrically and nonparametrically, respectively. Based on the parametric and nonparametric estimation of the weight function, two types of the score test are constructed. We investigate the finite sample property of our proposed tests through simulation studies.

The rest of this paper is organized as follows. In Sect. 2, we construct the test statistics and derive their asymptotic properties under null hypothesis and local alternative hypothesis. In Sect. 3, some simulation analysis and a real data analysis is carried out to illustrated the proposed tests. The proofs of the asymptotic results are presented in the Appendix.

## 2 Test procedure

### 2.1 Construction of test statistics

Let  $X = (U, V)$  and we assume that the covariate  $U$  is missing at random (MAR) throughout this paper, while  $Y, V$  and  $T$  are fully observed. Here  $U, V$  are  $p_1, p_2$ -dimensional random vectors, respectively. Let  $\delta$  be the missing indicator for the individual. It is defined as  $\delta = 1$  if  $U$  is observed and  $\delta = 0$  if otherwise. MAR implies that  $\delta$  and  $U$  are conditional independent given other variables  $Y, V$  and  $T$ . Thats,

$$P(\delta = 1|Y, U, V, T) = P(\delta = 1|Y, V, T) = \pi(Z),$$

here  $Z = (Y, V, T)$ . MAR is commonly assumed in the statistical analysis with missing data and is suitable in many practical situations, see Little and Rubin (1987).

Our tests are based on the consideration that under  $H_0$ , we have

$$E\left(\frac{\delta}{\pi(Z)}(Y - X^\tau \beta - g(T, \theta))\right) = 0, \quad (3)$$

while under alternative hypothesis with  $\Pr(g(T) = g(T, \theta)) < 1$ , we can obtain

$$E\left(\frac{\delta}{\pi(Z)}(Y - X^\tau \beta - g(T, \theta))\right) \neq 0.$$

Consequently, we can construct the following two residual-based test statistics based on the left hand side of the empirical version in (3)

$$T_{n1} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i)} (y_i - x_i^\tau \hat{\beta} - g(t_i, \hat{\theta})), \quad (4)$$

$$T_{n2} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\pi(z_i, \hat{\alpha})} (y_i - x_i^\tau \hat{\beta} - g(t_i, \hat{\theta})), \quad (5)$$

where  $\hat{\beta}, \hat{\theta}$  are the estimators of  $\beta, \theta$ , and  $\hat{\pi}(z_i)$  and  $\pi(z_i, \hat{\alpha})$  are the parametric and nonparametric estimators of  $\pi(z_i)$ , respectively. The parameter estimators  $\hat{\beta}$  and  $\hat{\theta}$ , and the function estimation  $\hat{\pi}(z_i)$  and  $\pi(z_i, \hat{\alpha})$  will be specified later. The difference between the test (4) and (5) is that the test (4) considers the estimator of  $\pi(z_i)$  to be nonparametric function while (5) considers that to be parametric form.

Let  $g_1(T) = E(\delta X|T)/E(\delta|T)$ ,  $g_2(T) = E(\delta Y|T)/E(\delta|T)$ , and their corresponding estimators are denoted by

$$\hat{g}_1(t) = \frac{\sum_{j=1}^n \delta_j x_j K_h(t - t_j)}{\sum_{j=1}^n \delta_j K_h(t - t_j)}, \quad \hat{g}_2(t) = \frac{\sum_{j=1}^n \delta_j y_j K_h(t - t_j)}{\sum_{j=1}^n \delta_j K_h(t - t_j)}$$

here  $K_h(\cdot) = K(\cdot/h)/h$  with  $K(\cdot)$  being a kernel function and  $h$  being a bandwidth. We estimate the regression parameters  $\beta$  by using the following expression:

$$\hat{\beta} = \left( \sum_{i=1}^n \delta_i (x_i - \hat{g}_1(t_i))(x_i - \hat{g}_1(t_i))^\tau \right)^{-1} \sum_{i=1}^n \delta_i (x_i - \hat{g}_1(t_i))(y_i - \hat{g}_2(t_i)).$$

Based on the above estimator for  $\hat{\beta}$ , the weighted least square estimator  $\hat{\theta}$  of  $\theta$  is defined as

$$\hat{\theta} = \arg \min_{\theta} \frac{1}{n} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i)} (y_i - x_i^\tau \hat{\beta} - g(t_i, \theta))^2,$$

or

$$\hat{\theta} = \arg \min_{\theta} \frac{1}{n} \sum_{i=1}^n \frac{\delta_i}{\pi(z_i, \hat{\alpha})} \left( y_i - x_i^\tau \hat{\beta} - g(t_i, \theta) \right)^2,$$

which is dependent on whether the inverse probability function is estimated parametrically or nonparametrically.

When the dimension of  $Z$  is not high and we do not have the idea about the form of  $\pi(Z)$ , we can apply the following kernel estimation method to estimate  $\pi(Z)$ , that's,

$$\hat{\pi}(z_i) = \frac{\sum_{j=1}^n \delta_j K_h(z_i - z_j)}{\sum_{j=1}^n K_h(z_i - z_j)}. \quad (6)$$

However, as verified in the literature, when the dimension of  $Z$  is high, the fully nonparametric kernel estimator may suffer from the curse of dimensionality and impede its use in practice. At this time, if we have some a priori knowledge about the structure of  $\pi(Z)$  which is also very common in practice, parametric estimation is another alterative method. For example, we assume that  $\pi(Z, \alpha)$  to be a logistic function based on  $\delta_i, y_i, t_i, i = 1, \dots, n$ . More specifically, we suppose  $\pi(z_i, \alpha) = (1 + \exp(-\alpha_0 - \alpha_1 y_i - \alpha_2 t_i - \alpha_3^\tau v_i))^{-1}$  where  $\alpha = (\alpha_0, \alpha_1, \alpha_2, \alpha_3)^\tau$  is an unknown vector parameter. We denote the maximum likelihood estimator of  $\alpha$  as  $\hat{\alpha} = (\hat{\alpha}_0, \hat{\alpha}_1, \hat{\alpha}_2, \hat{\alpha}_3)^\tau$ , and the corresponding estimator of  $\pi(z, \alpha)$  is

$$\pi(z_i, \hat{\alpha}) = (1 + \exp(-\hat{\alpha}_0 - \hat{\alpha}_1 y_i - \hat{\alpha}_2 t_i - \hat{\alpha}_3^\tau v_i))^{-1}. \quad (7)$$

When  $\pi(Z)$  is not parametric, the parametric method may obtain inconsistent estimator. However, from the numerical analysis of the paper, the test (5) is robust to the missing mechanisms. The estimators  $\hat{\pi}(z_i)$  and  $\pi(z_i, \hat{\alpha})$  in (4) and (5) are from that in (6) and (7), respectively.

## 2.2 Asymptotic behavior of the test statistics

Let  $\pi'(Z, \alpha) = \text{grad}_\alpha(\pi(Z, \alpha))$ ,  $g'(T, \theta) = \text{grad}_\theta(g(T, \theta))$ ,  $\Gamma = (1, Z)$ ,  $\Sigma_\alpha = E(\pi(Z, \alpha)(1 - \pi(Z, \alpha)\Gamma^\tau\Gamma))$  and  $\Sigma_\theta = E(g'(T, \theta)^\tau g'(T, \theta))$ . Under mild conditions, see [Jennrich \(1969\)](#), we have

$$\sqrt{n}(\hat{\theta} - \theta) = \Sigma_\theta^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n g'(t_i, \theta)^\tau \frac{\delta_i}{\hat{\pi}(z_i)} (y_i - x_i^\tau \hat{\beta} - g(t_i, \theta)) + o_p(1), \quad (8)$$

For the MLE estimator of  $\alpha$ ,  $\hat{\alpha}$ , we have

$$\sqrt{n}(\hat{\alpha} - \alpha) = \Sigma_\alpha^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n \Gamma^\tau (\delta_i - \pi(z_i, \alpha)) + o_p(1), \quad (9)$$

where the  $\hat{\pi}(z_i)$  should be updated as  $\pi(z_i, \hat{\alpha})$  when  $\pi(z_i)$  is estimated parametrically.

We first introduce some notations that are related to the limiting variance of the test statistic. Let  $\Sigma_0 = E[\delta(X - g_1(T))(X - g_1(T))^\tau]$ , and

$$\begin{aligned} A_1(t_i, \theta) &= 1 - Eg'(T, \theta)\Sigma_\theta^{-1}g'(t_i, \theta)^\tau, \\ A_2(\theta) &= E(X^\tau) - Eg'(T, \theta)\Sigma_\theta^{-1}E(g'(T, \theta)^\tau X^\tau), \\ M &= E((1 - \pi(Z, \alpha))\Gamma A_1(T, \theta)\epsilon), \\ L_1(x_i, t_i, \theta) &= A_1(t_i, \theta) - A_2(\theta)\Sigma_0^{-1}(x_i - g_1(t_i))\pi(z_i), \\ L_2(x_i, t_i, \theta) &= A_1(t_i, \theta) - A_2(\theta)\Sigma_0^{-1}(x_i - g_1(t_i))\pi(z_i, \alpha) \end{aligned}$$

Under null hypothesis, the asymptotic properties of  $T_{ni}$  ( $i = 1, 2$ ) in (4) and (5) are as follows.

**Theorem 1** *Under  $H_0$  and the conditions in appendix, we have*

$$T_{n1} \rightarrow N(0, V_1) \text{ and } T_{n2} \rightarrow N(0, V_2),$$

where

$$\begin{aligned} V_1 &= E\left(\frac{\delta\epsilon}{\pi(Z)}L_1(X, T, \theta) + \frac{\pi(Z) - \delta}{\pi(Z)}A_1(T, \theta)E(\epsilon|Z)\right)^2, \\ V_2 &= E\left(\frac{\delta\epsilon}{\pi(Z, \alpha)}L_2(X, T, \theta) - M\Sigma_\alpha^{-1}\Gamma^\tau(\delta - \pi(Z, \alpha))\right)^2. \end{aligned}$$

We now investigate the sensitive of the tests for a sequence of local alternatives with the form

$$H_{1n} : g(T) = g(T, \theta) + C_n G(T) + \eta, \quad (10)$$

where  $E(\eta|T) = 0$  and the function  $G(\cdot)$  satisfies  $E(G^2(T)) < \infty$ . Then we have the following theorem under  $H_{1n}$ ,

**Theorem 2** *Assume the same conditions as Theorem 1, under local alternatives  $H_{1n}$ , we have,*

- (i) *If  $n^{1/2}C_n \rightarrow 1$ ,  $T_{n1} \rightarrow N(\mu_1, V_1)$  and  $T_{n2} \rightarrow N(\mu_2, V_2)$ , where  $\mu_1 = \mu_2 = E(G(T)A_1(T, \theta))$ ;*
- (ii) *If  $n^r C_n \rightarrow a$  with  $0 < r < 1/2$  and  $a \neq 0$ , then  $T_{n1} \rightarrow \infty$  and  $T_{n2} \rightarrow \infty$ .*

We realize, from Theorem 2, that, when local alternatives are distinct from the null hypothesis at the rate  $n^{-r}$  with  $0 < r < 1/2$ , the proposed test in the paper can have asymptotic power 1; when that are distinct from the null hypothesis at the rate  $n^{-1/2}$ , the test can also detect alternatives. The rate  $n^{-1/2}$  is the possible fastest rate for lack-of-fit test.

The asymptotical properties of  $T_{n2}$  in Theorem 1 and 2 are from the assumption that  $\pi(Z, \alpha)$  is specified correctly. When the assumption is violated, we denote the

true probability function as  $\pi_0(Z, \tilde{\alpha})$  instead of  $\pi(Z, \alpha)$ . In this case, the left hand side in (3) can be proved that

$$E\left(\frac{\delta}{\pi(Z, \alpha)}(Y - X^\tau \beta - g(T, \theta))\right) = E\left[\frac{\pi_0(Z, \tilde{\alpha})}{\pi(Z, \alpha)} E((Y - X^\tau \beta - g(T, \theta))|Z)\right]. \quad (11)$$

Note that  $E((Y - X^\tau \beta - g(T, \theta))|Z) = E((Y - X^\tau \beta - g(T, \theta))|Y, V, T)$ , which may not be equal to zero, the term in (11) cannot be proved to be zero consequently. Hence, when  $\pi(z_i, \alpha)$  is misspecified, Theorem 1 and 2 are not corrected for the tests theoretically. In order to avoid this problem, in the paper, we also propose the test  $T_{n1}$  based on the nonparametric estimator of selection probability  $\pi(Z)$ .

*Remark 1* We establish the asymptotic normality of the test  $T_{n2}$  in Theorem 1 and 2 when  $\pi(Z, \alpha)$  is logistic regression. If  $\pi(Z, \alpha)$  is any other parametric function instead of logistics regression function, we can similarly obtain the corresponding asymptotic property of the test  $T_{n2}$  by modifying the asymptotical behavior of  $\hat{\alpha}$  in (9). Other popular parametric methods, such as generalized estimating equations (GEE), can also be applied to estimate the parameter  $\alpha$ . We only need to update the asymptotic expansion of  $\hat{\alpha}$  derived from other estimation procedures and the asymptotic result for the test  $T_{n2}$  should be changed correspondingly.

### 3 Numerical analysis

#### 3.1 Simulation study

In this section, we report results from several simulation studies to evaluate the finite sample behavior of the proposed test statistics, and generate 2,000 simulated data sets for all simulations. We take  $K(u) = 15/16(1 - u^2)^2$ , if  $|u| \leq 1$ ; 0 otherwise as the kernel function. Though bandwidth selection has been studied extensively in nonparametric estimation problem, it is still an open problem in model checking area as pointed out by Zhu and Ng (2003) and Zhu (2005). From our experience, a good empirical choice of the bandwidth is  $h_0 = \hat{\sigma}(T)n^{-1/3}$  here  $\hat{\sigma}(T)$  is the empirical estimator of the standard deviation of variable  $T$ . Evidently, this bandwidth satisfies condition (5) in Appendix. To investigate the sensitivity of the bandwidth selection, we also consider several bandwidth selection, that is,  $h_0 = \hat{\sigma}(T)n^{-1/3}$ ,  $h_1 = 0.5\hat{\sigma}(T)n^{-1/3}$  and  $h_2 = 2\hat{\sigma}(T)n^{-1/3}$ .

*Study 1.* The data was generated according to the following partial linear model

$$Y = \beta X + 1 + T + aT^2 + \varepsilon, \quad (12)$$

where  $\beta = 1$ ,  $X \sim N(0, 1)$ ,  $T \sim U(0, 1)$ ,  $\varepsilon \sim N(0, 0.4)$  and  $g(T) = 1 + T + aT^2$ . For model (12), the testing problem is whether  $g(T)$  is a linear function of  $1 + T$ , i.e.,  $H_0 : g(T) = \theta(1 + T)$  when  $X$  is missing. It is clear that  $a = 0$  is corresponding to the null hypothesis and  $a \neq 0$  to alternatives.

**Table 1** Simulated size and power under sample size  $n = 100$ , missing mechanisms  $\pi_1(y, t)$ , and different  $a$  for Study 1

$a$	$T_{n1}$			$T_{n2}$		
	$h_1$	$h_0$	$h_2$	$h_1$	$h_0$	$h_2$
0.0	0.054	0.052	0.061	0.051	0.055	0.055
0.2	0.060	0.065	0.072	0.102	0.100	0.105
0.4	0.186	0.185	0.200	0.259	0.238	0.248
0.6	0.398	0.390	0.410	0.477	0.482	0.480
0.8	0.652	0.659	0.660	0.719	0.737	0.739
1.0	0.840	0.868	0.856	0.879	0.885	0.900
1.2	0.950	0.950	0.952	0.963	0.963	0.971
1.4	0.987	0.987	0.983	0.995	0.994	0.989
1.6	0.997	0.999	0.998	0.995	0.998	0.997
1.8	0.999	1.000	1.000	0.999	1.000	0.999
2.0	1.000	1.000	1.000	0.999	1.000	1.000

Two missing probability mechanisms are chosen as follows:

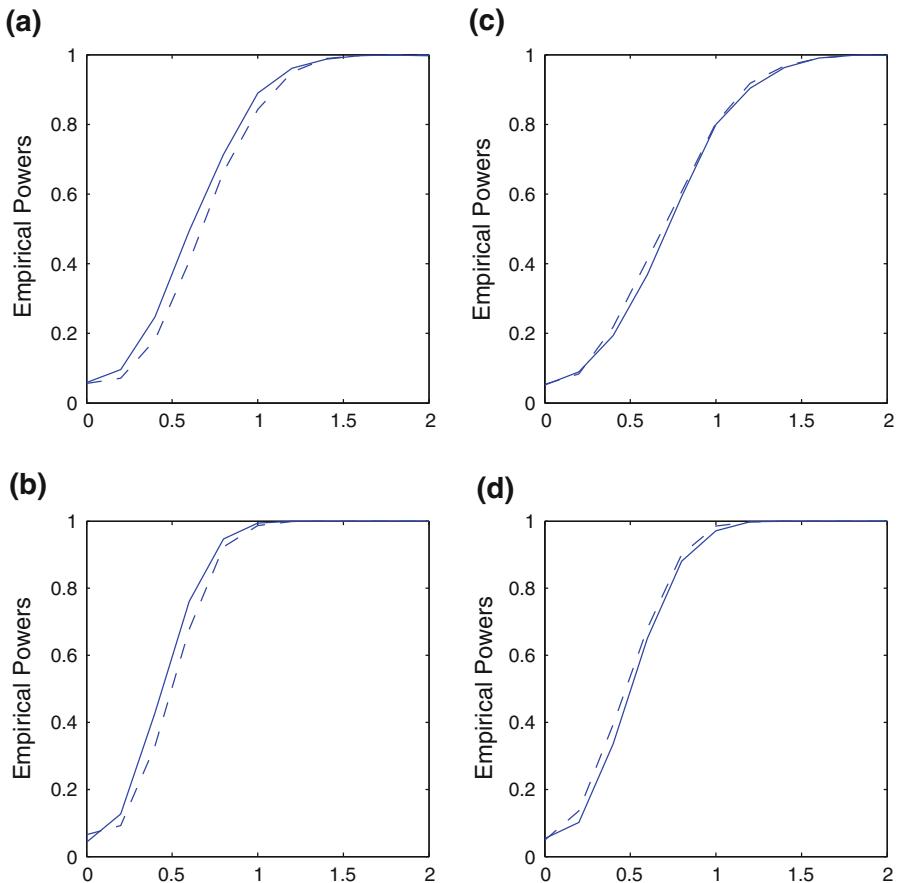
$$\begin{aligned}\pi_1(y, t) &= P(\delta = 1|Y = y, T = t) = 1/(1 + \exp(-(1 + y + t))), \\ \pi_2(y, t) &= P(\delta = 1|Y = y, T = t) = 1/(1 + 0.5y^2/(y^2 + t^2)).\end{aligned}$$

For the above two cases, the mean response rates are  $E\pi_1(y, t) \approx 0.91$  and  $E\pi_2(y, t) \approx 0.71$ , respectively. Furthermore,  $\pi_1(y, t)$  is a parametric function with logistic form, while  $\pi_2(y, t)$  does not have this form.

In this simulation, by varying the values of  $a$  in (12), the sample size  $n = 100, 200$  and missing mechanism  $\pi_i(y, t)$  ( $i = 1, 2$ ), we study the size and power performance of the proposed tests. Also, the effect of the bandwidth on the performance of the test is studied by choosing  $h = h_0, h_1$  and  $h_2$ . According to our simulation results, the size and power of the test statistics are not too sensitive for bandwidth  $h = h_0, h_1, h_2$ , we report the simulation results with sample size  $n = 100$  and missing mechanism  $\pi_1(y, t)$  in Table 1 for space consideration. All the simulation runs are shown in Fig. 1 for fixed bandwidth  $h = h_0$ .

From Table 1, we can know clearly that the bandwidth has little influence on the behavior of both tests. For example, the powers for  $T_{n1}$  with  $n = 100$  and  $a = 0.80$  are 0.652, 0.659 and 0.660, which are corresponding to  $h = h_1, h_0$  and  $h_2$ , respectively. While for  $T_{n2}$ , the corresponding powers at this time are 0.719, 0.737 and 0.739, which are corresponding to  $h = h_1, h_0$  and  $h_2$ , respectively.

Figure 1a and b present the plots with missing probability  $\pi_1(y, t)$ , while the plots with  $\pi_2(y, t)$  are depicted in Fig. 1c and d. From these two figures, we can observe that our proposed tests  $T_{n1}$  and  $T_{n2}$  maintain the significance level very well. For the alternative hypothesis, we can notice that the power increases quickly as  $a$  in (12) increases, i.e., the tests are very sensitive to the alternatives. Also, we can find that when the sample size is  $n = 200$ , the power performances of both tests improve much compared with that under sample size  $n = 100$ . Further, the proposed tests with



**Fig. 1** Empirical powers of tests for Study 1 with  $n = 100$  and  $n = 200$ : **a** for  $\pi_1(y, t)$  and  $n = 100$ ; **b** for  $\pi_1(y, t)$  and  $n = 200$ ; **c** for  $\pi_2(y, t)$  and  $n = 100$ ; **d** for  $\pi_2(y, t)$  and  $n = 200$ ; The dashed line is for  $T_{n1}$ , and the solid line is for  $T_{n2}$ . The model for generating data is  $Y = \beta X + 1 + T + aT^2 + \varepsilon$ , where  $\beta = 1$ ,  $X \sim N(0, 1)$ ,  $T \sim U(0, 1)$ ,  $\varepsilon \sim N(0, 0.4)$  and  $g(T) = 1 + T + aT^2$ . The null hypothesis is  $H_0 : g(T) = \theta(1 + T)$

missing probability mechanisms  $\pi_1(y, t)$  is more efficient than that with  $\pi_2(y, t)$ . Note that the mean response rates of  $\pi_1(y, t)$  is larger than that of  $\pi_2(y, t)$ ; we can conclude that larger sample size or more information generally improves the performance of the tests.

We turn to compare the tests  $T_{n1}$  and  $T_{n2}$ . We find that when the missing probability is  $\pi_1(y, t)$ , which is a logistics function,  $T_{n2}$  is more powerful than  $T_{n1}$ , while they are going in the opposite way with nonparametric missing mechanism  $\pi_2(y, t)$ . When we know the parametric form of the missing mechanism, using this information can generally produce more efficient checking procedure. On the other hand, if we misspecify the missing mechanism, parametric procedure may result in inferior power performance. However, we also notice that in this case, the performance of  $T_{n2}$  is still comparable to that of  $T_{n1}$ .

*Study 2.* We generate the data according to the following model

$$Y = \beta_1 X_1 + \beta_1 X_2 + \beta_2 X_3 + 1 + T + a \sin(2\pi T) + \varepsilon, \quad (13)$$

where  $\beta_1 = \beta_1 = \beta_2 = 1$ ,  $X_1, X_2, X_3 \sim N(0, 1)$ ,  $T \sim U(0, 1)$ ,  $\varepsilon \sim N(0, 0.4)$ , and  $g(T) = 1 + T + a \sin(2\pi T)$ . For model (13), we check whether  $g(T)$  is a linear function, i.e.,  $H_0 : g(T) = \theta(1 + T)$ . The null hypothesis is true when  $a = 0$ , and  $a \neq 0$  is corresponding to the alternative hypothesis. We also assume  $X_1$  missing is missing according to the following missing mechanisms:

$$\begin{aligned} \pi_1(y, x_2, x_3, t) &= 1/(1 + 0.25|y/(y + x_2 + x_3 + t)|); \\ \pi_2(y, x_2, x_3, t) &= 1/(1 + (y^2/(y^2 + x_2^2 + x_3^2 + t^2))). \end{aligned}$$

At this time, the mean response rates are  $E\pi_1(y, x_2, x_3, t) \approx 0.83$  and  $E\pi_2(y, x_2, x_3, t) \approx 0.67$ , respectively. For this study, we investigate the effect of dimension of the variables  $Z = (Y, X_2, X_3, T)$  on  $T_{n1}$  and the robustness of  $T_{n2}$  to the nonparametric missing mechanisms.

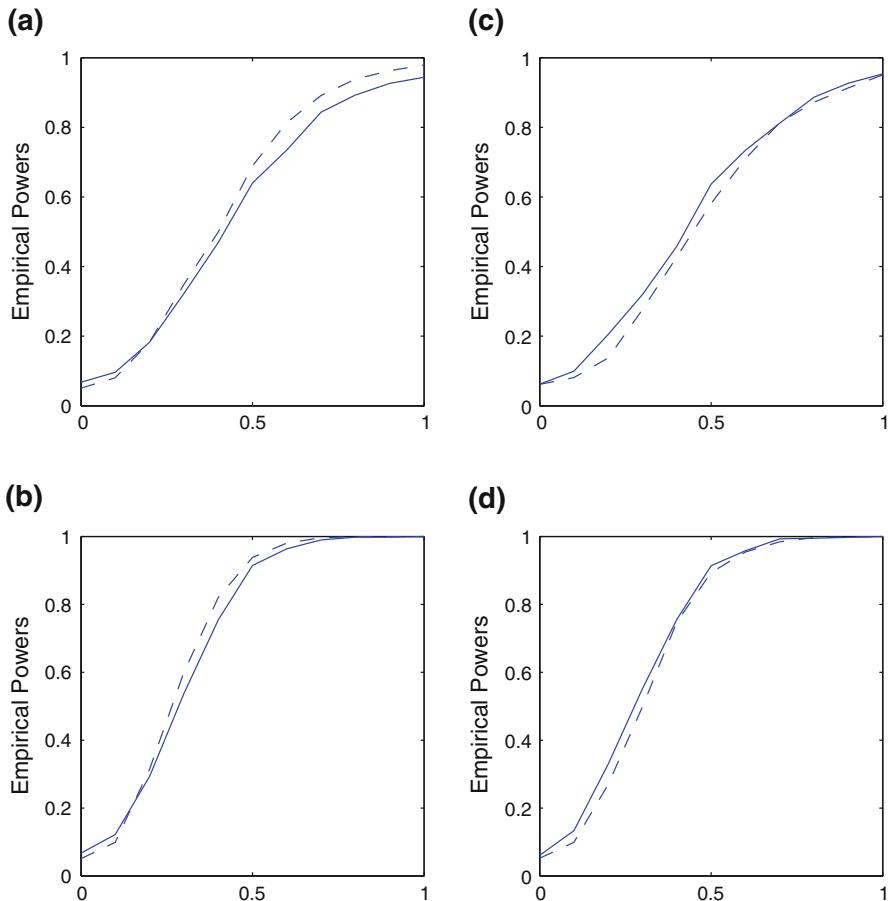
We show the results in Fig. 2a and b with  $\pi_1(y, x_2, x_3, t)$  and in Fig. 2c and d with  $\pi_2(y, x_2, x_3, t)$ . From this Figure, we can get the similar conclusions as Study 1, except the following findings. When the dimension of  $Z$  is four, the performance of  $T_{n1}$  is comparable. In other words,  $T_{n1}$  does not suffer the curse of dimension too much. Meanwhile, the test  $T_{n2}$  is robust to the missing mechanism, and it can perform very well even when the missing mechanism is not parametric.

### 3.2 Real data analysis

In this section, we apply our method to the analysis of an AIDS clinical trial group (ACTG 315) study. There are 53 HIV-1-infected patients treated, of which five patients quitted the study due to drug intolerance and other problems. Hence, 48 evaluable patients enrolled in ACTG 315. The response variable is viral load and the covariates are CD4+ cell counts and treatment time. All the patients are repeatedly measured, and a total of 317 observations are available from 48 patients with 64 CD4+ cell counts missing. That is, the missing proportion is 20.19 %. The data set has been studied by [Wu and Wu \(2001, 2002\)](#), and [Yang et al. \(2009\)](#) etc.

In general, immunologic response (measured by CD4+ cell count) and the virologic response (measured by viral load) are negatively correlated during antiviral treatments. It is suggested by [Liang et al. \(2004\)](#) that the impact of CD4+ cell count and treatment time on the viral load is linear and nonparametric, respectively. However, it is important to check whether the assumption about the nonparametric relationship between the viral load and the treatment time is validated or not. Note that this data set is actually longitudinal. We ignore the correlation structure for hypothesis testing since the proposed tests can be extended to a working independence analysis of longitudinal data, that is, the correlation structure is ignored as in [Liang et al. \(2004\)](#) and [Yang et al. \(2009\)](#).

Let  $Y$  be the viral load,  $T$  be the treatment time and  $X$  be the CD4+ cell counts. Denote  $\delta = 0$  if CD4+ is missing, otherwise  $\delta = 1$ . The following model is considered



**Fig. 2** Empirical powers of tests for Study 2 with  $n = 50$  and  $n = 100$ : **a** for  $\pi_1(y, x_2, x_3, t)$  and  $n = 50$ ; **b** for  $\pi_1(y, x_2, x_3, t)$  and  $n = 100$ ; **c** for  $\pi_2(y, x_2, x_3, t)$  and  $n = 50$ ; **d** for  $\pi_2(y, x_2, x_3, t)$  and  $n = 100$ ; The dashed line is for  $T_{n1}$ , and the solid line is for  $T_{n2}$ . The model for generating data is  $Y = \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_3 + 1 + T + a \sin(2\pi T) + \varepsilon$ , where  $\beta_1 = \beta_2 = \beta_3 = 1$ ,  $X_i \sim N(0, 1)$ , ( $i = 1, 2, 3$ ),  $T \sim U(0, 1)$ ,  $\varepsilon \sim N(0, 0.4)$  and  $g(T) = 1 + T + a \sin(2\pi T)$ . The null hypothesis is  $H_0 : g(T) = \theta(1 + T)$

for data fitting:

$$Y = X\beta + g(T) + \varepsilon. \quad (14)$$

For models (14), we want to check whether the term  $g(T)$  in (14) is linear or not. Both the  $p$  values for  $T_{n1}$  and  $T_{n2}$  are 0.000 for the null hypothesis  $H_0 : g(T) = \theta T$ . Thus we can reject the null hypothesis, and the linear form of  $g(T)$  is not feasible. The result suggests that the nonparametric function  $g(T)$  is appropriate in model (14) as in Liang et al. (2004) and Yang et al. (2009).

## Appendix: Proof of the theorems

The following conditions are required for the theorems in Sect. 2.

1.  $g(\cdot, \theta)$  is continuously differentiable with respect to  $\theta$  in the interior set of  $\Theta$ , and  $g_1(\cdot)$  and  $g_2(\cdot)$  satisfy Lipschitz condition of order 1;
2.  $\pi(z)$  has bounded partial derivatives up to order  $k (> 2)$  almost surely;
3.  $\Sigma_0, \Sigma_\alpha, \Sigma_\theta$  are all positive definite matrix;
4.  $\sup E(\varepsilon^2 | X = x, T = t) < c_1$  for some  $c_1$  and all  $x$  and  $t$ ,  $E|X|^4 < \infty$ , and  $E|Y|^4 < \infty$ ;
5. As  $n \rightarrow \infty$ ,  $\sqrt{n}h^2 \rightarrow 0$ , and  $\sqrt{n}h \rightarrow \infty$ ;
6. The density of  $Z$ , say  $f(z)$  on support  $\mathcal{C}$ , exists and has bounded derivatives up to order 2 and satisfies

$$0 < \inf_{z \in \mathcal{C}} f(z) \leq \sup_{z \in \mathcal{C}} f(z) < \infty;$$

7. The continuous kernel function  $K(\cdot)$  satisfies: (i) the support of  $K(\cdot)$  is the interval  $[-1, 1]$ ; (ii)  $K(\cdot)$  is symmetric about 0; iii)  $\int_{-1}^1 K(u)du = 1$  and  $\int_{-1}^1 |u|K(u)du \neq 0$ .

*Remark 2* Conditions (1), (5) and (7) are typical for obtaining convergence rates when nonparametric estimation is applied. Condition (2) is a common assumption in missing data study, which is also used in Wang et al. (2004), and so on. The conditions (3) and (4) are necessary for the asymptotic normality of the least squares estimator. Condition (6) is a typical condition for avoiding the boundary effect for nonparametric estimate.

**Lemma 1** *Under conditions 1–7 in the Appendix, the asymptotic properties of  $\sqrt{n}(\hat{\beta} - \beta)$  under the null hypothesis in (2) or the local alternatives in (10) are the same as follows*

$$\sqrt{n}(\hat{\beta} - \beta) = \frac{\Sigma_0^{-1}}{\sqrt{n}} \sum_{i=1}^n \delta_i(x_i - g_1(t_i))\epsilon_i + o_p(1).$$

*Proof for Lemma 1* Under the null hypothesis, we have

$$\begin{aligned} \sqrt{n}(\hat{\beta} - \beta) &= \frac{\Sigma_0^{-1}}{\sqrt{n}} \sum_{i=1}^n \delta_i(x_i - g_1(t_i))\{y_i - g_2(t_i) - (x_i - g_1(t_i))^\tau \beta\} + o_p(1) \\ &= \frac{\Sigma_0^{-1}}{\sqrt{n}} \sum_{i=1}^n \delta_i(x_i - g_1(t_i))(y_i - x_i^\tau \beta - g(t_i, \theta)) + o_p(1) \\ &= \frac{\Sigma_0^{-1}}{\sqrt{n}} \sum_{i=1}^n \delta_i(x_i - g_1(t_i))\epsilon_i + o_p(1). \end{aligned}$$

Under the local alternatives, we have

$$\begin{aligned}\sqrt{n}(\hat{\beta} - \beta) &= \frac{\Sigma_0^{-1}}{\sqrt{n}} \sum_{i=1}^n \delta_i(x_i - g_1(t_i))\{y_i - g_2(t_i) - (x_i - g_1(t_i))^T \beta\} + o_p(1) \\ &= \frac{\Sigma_0^{-1}}{\sqrt{n}} \sum_{i=1}^n \delta_i(x_i - g_1(t_i))(y_i - x_i^\tau \beta - g(t_i, \theta) - C_n G(t_i)) + o_p(1) \\ &= \frac{\Sigma_0^{-1}}{\sqrt{n}} \sum_{i=1}^n \delta_i(x_i - g_1(t_i))\epsilon_i + o_p(1).\end{aligned}$$

Thus, Lemma 1 is proved.  $\square$

*Proof of Theorem 1* First, we prove the asymptotical distribution of  $T_{n1}$  under null hypothesis. It can be verified that

$$\begin{aligned}T_{n1} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i)} (y_i - x_i^\tau \beta - g(t_i, \theta)) - \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i)} x_i^\tau (\hat{\beta} - \beta) \\ &\quad - \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i)} g'(t_i, \theta)(\hat{\theta} - \theta) \\ &= T_{n11} - T_{n12} - T_{n13}. \tag{15}\end{aligned}$$

For  $T_{n12}$  in (15), it can be verified that

$$\begin{aligned}T_{n12} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\pi(z_i)} x_i^\tau (\hat{\beta} - \beta) + \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{(\pi(z_i) - \hat{\pi}(z_i))\delta_i}{\pi^2(z_i)} x_i^\tau (\hat{\beta} - \beta) + o_p(1) \\ &= E(X^\tau) \sqrt{n}(\hat{\beta} - \beta) \\ &\quad + \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\sum_{j=1}^n (\pi(z_i) - \delta_j) K_h(z_j - z_i) \delta_j x_i^\tau}{\pi^2(z_i) n f(z_i)} (\hat{\beta} - \beta) + o_p(1) \\ &= E(X^\tau) \sqrt{n}(\hat{\beta} - \beta) + \frac{1}{\sqrt{n}} \sum_{j=1}^n \frac{\pi(z_j) - \delta_j}{\pi(z_j)} E(X^\tau | z_j) (\hat{\beta} - \beta) + o_p(1) \\ &= E(X^\tau) \sqrt{n}(\hat{\beta} - \beta) + o_p(1). \tag{16}\end{aligned}$$

The last equation follows from the fact that  $n^{-1} \sum_{i=1}^n (\pi(z_i) - \delta_i) \pi(z_i)^{-1} E(X^\tau | z_i) = o_p(1)$  and  $\sqrt{n}(\hat{\beta} - \beta) = O_p(1)$ .

For  $T_{n13}$  in (15), we have

$$\begin{aligned}
 T_{n13} &= E(g'(T, \theta))\sqrt{n}(\hat{\beta} - \beta) \\
 &= E(g'(T, \theta))\Sigma_\theta^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n g'(t_i, \theta)^\tau \frac{\delta_i}{\hat{\pi}(z_i)} (y_i - x_i^\tau \hat{\beta} - g(t_i, \theta)) + o_p(1) \\
 &= E(g'(T, \theta))\Sigma_\theta^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i)} g'(t_i, \theta)^\tau (\epsilon_i - x_i^\tau (\hat{\beta} - \beta)) + o_p(1) \\
 &= E(g'(T, \theta))\Sigma_\theta^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n g'(t_i, \theta)^\tau \frac{\delta_i \epsilon_i}{\hat{\pi}(z_i)} \\
 &\quad - E(g'(T, \theta))\Sigma_\theta^{-1} E(g'(T, \theta)^\tau X^\tau) \sqrt{n}(\hat{\beta} - \beta) + o_p(1). \tag{17}
 \end{aligned}$$

Based on the expressions (15), (16) and (17), and note that

$$\begin{aligned}
 A_1(t_i, \theta) &= 1 - Eg'(T, \theta)\Sigma_\theta^{-1}g'(t_i, \theta)^\tau; \\
 A_2(\theta) &= E(X^\tau) - Eg'(T, \theta)\Sigma_\theta^{-1}E(g'(T, \theta)^\tau X^\tau),
 \end{aligned}$$

we can get

$$T_{n1} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i \epsilon_i}{\hat{\pi}(z_i)} A_1(t_i, \theta) - A_2(\theta) \sqrt{n}(\hat{\beta} - \beta) + o_p(1). \tag{18}$$

According to Lemma 1, for  $\hat{\beta}$ , we have

$$\sqrt{n}(\hat{\beta} - \beta) = \Sigma_0^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n \delta_i (x_i - g_1(t_i)) \epsilon_i + o_p(1).$$

Note that,

$$\frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i \epsilon_i}{\hat{\pi}(z_i)} A_1(t_i, \theta) = \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i \epsilon_i + (\pi(z_i) - \delta_i) E(\epsilon | z_i)}{\pi(z_i)} A_1(t_i, \theta) + o_p(1),$$

the expression  $T_{n1}$  in (18) can be further derived as:

$$\begin{aligned}
 T_{n1} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i \epsilon_i}{\pi(z_i)} \{A_1(t_i, \theta) - A_2(\theta) \Sigma_0^{-1} (x_i - g_1(t_i)) \pi(z_i)\} \\
 &\quad + \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\pi(z_i) - \delta_i}{\pi(z_i)} A_1(t_i, \theta) E(\epsilon | z_i) + o_p(1).
 \end{aligned}$$

Then the asymptotical distribution of  $T_{n1}$  in Theorem 1 is proved.

Below we prove the asymptotical distribution of  $T_{n2}$ , it can be easily derived that

$$\begin{aligned} T_{n2} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i, \alpha)} (y_i - x_i^\tau \beta - g(t_i, \theta)) - \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i, \alpha)} x_i^\tau (\hat{\beta} - \beta) \\ &\quad - \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i}{\hat{\pi}(z_i, \alpha)} g'(t_i, \theta) (\hat{\theta} - \theta) \\ &= T_{n21} - T_{n22} - T_{n23}. \end{aligned} \quad (19)$$

For  $T_{n22}$  in (19), we have

$$\begin{aligned} T_{n22} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \left[ \frac{\delta_i x_i^\tau}{\pi(z_i, \alpha)} (\hat{\beta} - \beta) - \frac{(\pi(z_i, \hat{\alpha}) - \pi(z_i, \alpha)) \delta_i x_i^\tau}{\pi^2(z_i, \alpha)} (\hat{\beta} - \beta) \right] + o_p(1) \\ &= T_{n22,1} - T_{n22,2} + o_p(1). \end{aligned} \quad (20)$$

Note that  $\Gamma_i = (1, z_i)$ ,  $\sqrt{n}(\hat{\alpha} - \alpha) = O_p(1)$  and  $\pi(z_i, \hat{\alpha}) - \pi(z_i, \alpha) = \pi'(z_i, \alpha)(\hat{\alpha} - \alpha) + o_p(n^{-1/2}) = \pi(z_i, \alpha)(1 - \pi(z_i, \alpha))\Gamma_i(\hat{\alpha} - \alpha) + o_p(n^{-1/2})$ , for  $T_{n22,2}$ , we have

$$T_{n22,2} = E((1 - \pi(Z, \alpha))\Gamma X^\tau) \sqrt{n}(\hat{\alpha} - \alpha)(\hat{\beta} - \beta) + o_p(1) = o_p(1).$$

Consequently,  $T_{n22} = E(X^\tau) \sqrt{n}(\hat{\beta} - \beta)$ .

For  $T_{n23}$  in (19), it can be proved that

$$\begin{aligned} T_{n23} &= Eg'(T, \theta) \sqrt{n}(\hat{\theta} - \theta) \\ &= Eg'(T, \theta) \Sigma_\theta^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n g'(t_i, \theta)^\tau \frac{\delta_i \epsilon_i}{\pi(z_i, \hat{\alpha})} \\ &\quad - Eg'(T, \theta) \Sigma_\theta^{-1} E(g'(T, \theta)^\tau X^\tau) \sqrt{n}(\hat{\beta} - \beta) + o_p(1). \end{aligned} \quad (21)$$

According to the Eqs. (19), (20) and (21), we have

$$\begin{aligned} T_{n2} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i \epsilon_i}{\pi(z_i, \hat{\alpha})} A_1(t_i, \theta) - A_2(\theta) \sqrt{n}(\hat{\beta} - \beta) + o_p(1) \\ &= \bar{T}_{n21} - \bar{T}_{n22} + o_p(1). \end{aligned} \quad (22)$$

For  $\bar{T}_{n21}$ , it can be verified that

$$\begin{aligned} \bar{T}_{n21} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n A_1(t_i, \theta) \left[ \frac{\delta_i \epsilon_i}{\pi(z_i, \alpha)} - \frac{(\pi(z_i, \hat{\alpha}) - \pi(z_i, \alpha)) \delta_i \epsilon_i}{\pi^2(z_i, \alpha)} \right] + o_p(1) \\ &= \frac{1}{\sqrt{n}} \sum_{i=1}^n A_1(t_i, \theta) \frac{\delta_i \epsilon_i}{\pi(z_i, \alpha)} - M \sqrt{n}(\hat{\alpha} - \alpha), \end{aligned} \quad (23)$$

where  $M = E((1 - \pi(Z, \alpha))\Gamma A_1(T, \theta)\epsilon)$ .

Following lemma 1 and the Eqs. (22) and (23), we obtain

$$\begin{aligned} T_{n2} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i \epsilon_i}{\pi(z_i, \alpha)} \left[ A_1(t_i, \theta) - A_2(\theta) \Sigma_0^{-1}(x_i - g_1(t_i)) \pi(z_i, \alpha) \right] \\ &\quad - M \Sigma_\alpha^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n \Gamma^\tau (\delta_i - \pi(z_i, \alpha)) + o_p(1). \end{aligned}$$

Then the asymptotical distribution of  $T_{n2}$  in Theorem 1 is proved, and Theorem 1 is proved.  $\square$

*Proof of Theorem 2* For  $T_{n1}$ , it can be divided as

$$\begin{aligned} T_{n1} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i (\eta_i + C_n G(t_i))}{\hat{\pi}(z_i)} A_1(t_i, \theta) - A_2(\theta) \sqrt{n} (\hat{\beta} - \beta) + o_p(1) \\ &= \tilde{T}_{n11} + \tilde{T}_{n12} - \tilde{T}_{n13} + o_p(1). \end{aligned}$$

For  $\tilde{T}_{n12}$ , we can easily obtain

$$\begin{aligned} \tilde{T}_{n12} &= \frac{C_n}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i G(t_i)}{\pi(z_i)} A_1(t_i, \theta) + \frac{C_n}{\sqrt{n}} \sum_{i=1}^n \frac{(\pi(z_i) - \delta_i) G(t_i)}{\pi(z_i)} A_1(t_i, \theta) + o_p(1) \\ &= C_n \sqrt{n} E(G(T) A_1(T, \theta)) + o_p(1), \end{aligned}$$

where the last equation follows according to the fact that

$$Var \left( \frac{C_n}{\sqrt{n}} \sum_{i=1}^n \frac{(\pi(z_i) - \delta_i) G(t_i) A_1(t_i, \theta)}{\pi(z_i)} \right) = C_n^2 Var \left( \frac{(\pi(Z) - \delta) G(T) A_1(T, \theta)}{\pi(Z)} \right) \rightarrow 0.$$

From Lemma 1, we know

$$\sqrt{n} (\hat{\beta} - \beta) = \Sigma_0^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n \delta_i (x_i - G_1(t_i)) \epsilon_i + o_p(1).$$

As a result, if  $n^{1/2} C_n \rightarrow 1$ , we can obtain

$$\begin{aligned} T_{n1} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i \epsilon_i}{\pi(z_i)} \{A_1(t_i, \theta) - A_2(\theta) \Sigma_0^{-1}(x_i - g_1(t_i)) \pi(z_i)\} \\ &\quad + \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\pi(z_i) - \delta_i}{\pi(z_i)} A_1(t_i, \theta) E(\epsilon | z_i) + E(G(T) A_1(T, \theta)) + o_p(1). \end{aligned}$$

If  $n^r C_n \rightarrow a$ ,  $0 < r < 1/2$ , then it yields  $\sqrt{n}C_n \rightarrow \infty$ , as  $n \rightarrow \infty$ . As a result, we have  $T_{n1} \rightarrow \infty$ .

We investigate the asymptotic property of  $T_{n2}$  below. Note that

$$\begin{aligned} T_{n2} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i(\eta_i + C_n G(t_i))}{\pi(z_i, \hat{\alpha})} A_1(t_i, \theta) - A_2(\theta) \sqrt{n}(\hat{\beta} - \beta) + o_p(1) \\ &= \tilde{T}_{n21} + \tilde{T}_{n22} - \tilde{T}_{n23} + o_p(1). \end{aligned}$$

For  $\tilde{T}_{n22}$ , it can be derived that

$$\begin{aligned} \tilde{T}_{n22} &= \frac{C_n}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i G(t_i)}{\pi(z_i, \alpha)} A_1(t_i, \theta) \\ &\quad - \frac{C_n}{\sqrt{n}} \sum_{i=1}^n \frac{(\pi(z_i, \hat{\alpha}) - \pi(z_i, \alpha))\delta_i G(t_i)}{\pi^2(z_i, \alpha)} A_1(t_i, \theta) + o_p(1) \\ &= C_n \sqrt{n} E(G(T) A_1(T, \theta)) \\ &\quad - C_n E[(1 - \pi(Z, \alpha))G(T) A_1(T, \theta)\Gamma] \sqrt{n}(\hat{\alpha} - \alpha) + o_p(1) \\ &= C_n \sqrt{n} E(G(T) A_1(T, \theta)) + o_p(1). \end{aligned}$$

The last equation follows because  $\sqrt{n}(\hat{\alpha} - \alpha) = O_p(1)$  and  $C_n \rightarrow 0$ .

Consequently, according to Lemma 1, we have

$$\begin{aligned} T_{n2} &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{\delta_i \epsilon_i}{\pi(z_i, \alpha)} \left[ A_1(t_i, \theta) - A_2(\theta) \Sigma_0^{-1}(x_i - g_1(t_i)) \pi(z_i, \alpha) \right] \\ &\quad - M \Sigma_\alpha^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n \Gamma^\tau (\delta_i - \pi(z_i, \alpha)) + C_n \sqrt{n} E(G(T) A_1(T, \theta)). \end{aligned}$$

The asymptotic properties of  $T_{n2}$  can be obtained based on the above equation. Thus, Theorem 2 is proved.  $\square$

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