# ON CORRECT SELECTION FOR A RANKING PROBLEM

W. K. CHIU

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#### Abstract

Given k populations which belong to the exponential class, and having specified two positive constants  $(\delta^*, P^*)$ , an experimenter wishes to select t populations which (a) exclude all those populations with a parameter value not greater than the tth largest parameter value minus  $\delta^*$ , and (b) include all those populations with a parameter value not smaller than the (t+1)th largest parameter value plus  $\delta^*$ . This paper shows that the probability of successfully making such a selection, called a  $\delta^*$ -correct selection, is at least  $P^*$  if the basic sequential procedure,  $P_B^*$ , of Bechhofer, et al. [3] is used. This result includes the corresponding old result of their book (p. 129) as a particular case.

### 1. Introduction

Selecting the best t from among k populations is one of the most important ranking problems and has wide practical application. Bechhofer, Kiefer and Sobel ([3], p. 255) have formulated the problem in the following way: An experimenter is given  $k (\ge 2)$  populations  $\pi_1$ ,  $\dots$ ,  $\pi_k$ , whose density functions are members of the same univariate exponential (Koopman-Darmois) family:

$$f(x_i) = \exp\{P(x_i)\tau_i + R(x_i) + V(\tau_i)\}\$$
  $(i=1,\dots,k)$ 

where P(x), R(x), and  $V(\tau)$  are known functions. The populations are assumed to differ at most in the unknown parameter values  $\tau_i$  (i=1,  $\cdots$ , k). Let the ranked  $\tau$ -values be denoted by

$$\tau_{[1]} \leq \tau_{[2]} \leq \cdots \leq \tau_{[k]}$$

and the differences between any pair of them be denoted by:

$$\delta_{i,j} = \tau_{[i]} - \tau_{[j]}$$
  $(i \ge j; i, j = 1, \dots, k)$ .

It is assumed that the true pairing of  $\pi_i$  with  $\tau_{[j]}$   $(i, j=1, \cdots, k)$ 

is unknown to the experimenter, who is interested in selecting an unordered set of  $t (\ge 1)$  'best' populations, which are associated with the t largest parameter values  $\tau_{[k-t+1]}, \dots, \tau_{[k]}$ . Before the experimentation, the experimenter has to specify a pair of constants, as below:

(1) 
$$\{\delta^*, P^*\}, \text{ with } 0 < \delta^* < \infty \text{ and } 1 / \binom{k}{t} < P^* < 1 ,$$

with the intention to achieve the following probability requirement:

(2) 
$$\Pr \{ \text{Correct selection} | \delta_{k-t+1,k-t} \geq \delta^* \} = P^*.$$

Bechhofer, et al. [3] have proposed an interesting sequential sampling procedure,  $P_B^*$ , and have proved that their procedure guarantees the probability requirement (2) (p. 129). We shall describe the procedure in the next section. Two outstanding features of the procedure are: (a) The same procedure is applicable to a large number of distributions, including the normal, the exponential, Poisson, Bernoulli, and the negative binomial distributions, which belong to the exponential family; (b) The average sample number is, in general, considerably smaller than the sample size for a single-sample procedure.

However, the formulation of the problem has a fundamentally restrictive character in that its goal as expressed in (2) requires the condition:  $\delta_{k-t+1,k-t} \ge \delta^*$ . In practice, the experimenter would be unlikely to know that this can be satisfied. If  $\delta_{k-t+1,k-t} < \delta^*$ , then he does not know what alternate probability the sequential procedure can guarantee him. Further, in specifying the constants  $\{\delta^*, P^*\}$  the experimenter usually has some economic consideration in mind so that  $\delta^*$  is the smallest difference in parameter values that he wishes to detect, and he is indifferent to incorrect selections made in the zone  $\tau_{[k-t+1]} - \delta^* < \tau_{[k-t]} + \delta^*$ . Indeed he must be more interested in the probability of making such a selection than the conditional probability of (2).

Bechhofer, et al. [3] are well aware of these conditions and have proposed a related 'unsolved problem' in their book (p. 337), which we will restate with minor modifications. For any configuration of the parameter values, denoted as a k-vector:  $\vec{\tau} = (\tau_{[1]}, \dots, \tau_{[k]})$ , there are unique integers r and s satisfying  $0 \le r \le k - t$ ,  $0 \le s \le t$ , and such that

(3) 
$$\tau_{[r]} \leq \tau_{[k-t+1]} - \delta^* < \tau_{[r+1]} \text{ and } \tau_{[k-s]} < \tau_{[k-t]} + \delta^* \leq \tau_{[k-s+1]}$$
.

Here it is understood that  $\tau_{[0]} = -\infty$  and  $\tau_{[k+1]} = \infty$ . Thus there are r populations with  $\tau$ -values  $\leq \tau_{[k-t+1]} - \delta^*$ , and s populations with  $\tau$ -values  $\geq \tau_{[k-t]} + \delta^*$ . In this situation, the experimenter might reasonably still want the t selected populations (a) to exclude all those with a parameter value not greater than the tth largest parameter value minus  $\delta^*$ , namely, the r populations corresponding to the parameter values  $\tau_{[1]}$ ,

 $\cdots$ ,  $\tau_{[r]}$ , and (b) to include all those with a parameter value not smaller than the (t+1)th largest parameter value plus  $\delta^*$ , namely, the s populations corresponding to the parameter values  $\tau_{[k-s+1]}, \cdots, \tau_{[k]}$ . To clarify some notational problem, we should note that when r=0 the experimenter would not specifically intend to exclude any population because then every population mean is within  $\delta^*$  from  $\tau_{[k-t+1]}$ . Likewise, when s=0 the experimenter would not specifically intend to include any particular population because then no population mean is large enough to exceed  $\tau_{[k-t]} + \delta^*$ . Let us call any such selection a ' $\delta^*$ -correct selection'. (Bechhofer, et al. have not named it for the  $\{\delta^*, P^*\}$ -approach, although they have called it a 'correct decision' for a decision theoretic approach, p. 47.) Bechhofer, et al. conjecture that their sequential procedure,  $P_B^*$ , still guarantees that the probability of making a  $\delta^*$ -correct selection is at least  $P^*$ . This paper proves their conjecture.

## 2. The sequential procedure $P_R^*$

We shall refer to pp. 125 and 256 of Bechhofer, et al. [3] for the description of the sequential procedure  $P_B^*$ . At each stage of sampling, one observation is taken from each of the k populations. Let  $X_{ij}$  denote the chance variable corresponding to the jth observation taken from the populations  $\pi_i$   $(i=1,\dots,k;\ j=1,2,\dots)$ . They are assumed to be mutually independent. At the mth stage of experimentation  $(m=1,2,\dots)$  the values,  $y_{im}$ , of the sufficient statistics:

$$Y_{im} = \sum_{j=1}^{m} P(X_{ij})$$
  $(i=1,\dots,k)$ 

will be used for decision making. Denoting by  $y_{[1]m} \leq \cdots \leq y_{[k]m}$  and  $Y_{[1]m} \leq \cdots \leq Y_{[k]m}$  the ranked  $y_{im}$  and the ranked  $Y_{im}$   $(i=1,\dots,k;\ m=1,2,\dots)$ , respectively, we may introduce two k-vectors:

$$\vec{y}_m = (y_{\lceil 1 \rceil m}, \cdots, y_{\lceil k \rceil m}), \qquad \vec{Y}_m = (Y_{\lceil 1 \rceil m}, \cdots, Y_{\lceil k \rceil m}).$$

Let C denote the set of  $k!/\{(k-t)!t!\}$  ways of choosing t integers from the set  $\{1, 2, \dots, k\}$ . Any element of C can be represented by  $\gamma = \{\gamma_1, \dots, \gamma_t\}$  where  $\gamma_i$   $(i=1,\dots,t)$  are different positive integers not larger than k. The particular element  $\{k-t+1,\dots,k\}$  will be denoted by  $\gamma_e$ . We define, for any  $\gamma \in C$ , the product:

$$\gamma \vec{y}_m = \sum_{i=1}^t y_{[r_i]_m}$$
.

The rules for the procedure  $P_B^*$  are as follows. After the mth stage of observation, the experimenter calculates the quantity

$$Q^*(\vec{\boldsymbol{y}}_m) = \frac{\exp\left\{\delta^*\gamma_{\epsilon}\vec{\boldsymbol{y}}_m\right\}}{\sum\limits_{\gamma \in C} \exp\left\{\delta^*\gamma_{\epsilon}\vec{\boldsymbol{y}}_m\right\}}.$$

If  $Q^*(\vec{y}_m) < P^*$ , he continues to the (m+1)th stage of the experimentation. If  $Q^*(\vec{y}_m) \ge P^*$ , he terminates the experimentation and selects the t populations associated with the t largest observed values  $y_{[k-t+1]m}, \dots, y_{[k]m}$ . Bechhofer, et al. ([3], p. 129) have proved that  $P_B^*$  guarantees the probability of a correct selection to be not smaller than  $P^*$  whenever  $\delta_{k-t+1,k-t} \ge \delta^*$ , namely,

(5) Pr {Correct selection 
$$|\delta_{k-t+1,k-t} \ge \delta^*$$
} = E { $Q^*(\vec{Y}_n)$ }  $\ge P^*$ ,

where  $\vec{Y}_n$  is the terminal decision vector for the procedure.

#### 3. $\delta^*$ -correct selection

Let us consider the general configuration  $\vec{\tau} = (\tau_{[1]}, \dots, \tau_{[k]})$  in which  $\delta_{k-t+1,k-t}$  is not necessarily  $\geq \delta^*$ , as explained in Section 1. Our goal is to select t populations which exclude all those populations with parameter values  $\leq \tau_{[k-t+1]} - \delta^*$  and include all those populations with parameter values  $\geq \tau_{[k-t]} + \delta^*$ . Let  $S_k$  be the set (which is in fact a symmetric group) of k! permutations on the integers  $1, 2, \dots, k$ . If  $\alpha = (\alpha_1, \dots, \alpha_k)$  is any element of  $S_k$  we define  $\alpha \vec{y}_m = (y_{[\alpha_1]m}, \dots, y_{[\alpha_k]m})$ , which is a k-vector; also, we define the inner product

$$\vec{\tau} \cdot \alpha \vec{y}_m = \sum_{i=1}^k \tau_{[i]} y_{[\alpha_i]m}$$
.

Let two subsets of  $S_k$  be defined as follows:

$$S = \{\alpha : \alpha_i > k - t \text{ for some } i \leq r \text{ or } \alpha_j \leq k - t \text{ for some } j \geq k - s + 1\}$$
,  
 $T = \{\alpha : \alpha_i \leq k - t \text{ for all } i \leq r \text{ and } \alpha_i > k - t \text{ for all } j \geq k - s + 1\}$ .

Clearly, S and T are disjoint and they exhaust  $S_k$ . Assume that procedure  $P_B^*$  is used for the selection. Following the arguments of Sections 4.2, 5.4, and 6.1.1 of Bechhofer, et al. [3] we have the following expression:

(6) 
$$\Pr \{\delta^* \text{-correct selection}\} = \mathbb{E} \{Q(\vec{Y}_n)\},$$

where  $\vec{Y}_n$  is the terminal decision vector of the procedure and the quantity  $Q(\vec{y}_m)$ , at the *m*th stage of sampling, is defined to be:

(7) 
$$Q(\vec{y}_m) = \frac{\sum_{\alpha \in T} \exp \{\vec{\tau} \cdot \alpha \vec{y}_m\}}{\sum_{\alpha \in S_k} \exp \{\vec{\tau} \cdot \alpha \vec{y}_m\}}.$$

We are now in a position to prove the following theorem.

THEOREM. Let two constants  $\{\delta^*, P^*\}$  be specified as in (1), and let  $\vec{\tau} = (\tau_{[1]}, \dots, \tau_{[k]})$  be any configuration of the parameter values. For the selection of t populations which exclude all those populations with a  $\tau$ -value  $\leq \tau_{[k-t+1]} - \delta^*$  and include all those populations with a  $\tau$ -value  $\geq \tau_{[k-t]} + \delta^*$  by the sequential procedure  $P_R^*$ , we have:

(8) 
$$\Pr\{\delta^*\text{-correct selection}\} \geq P^*$$
.

PROOF. Let the integers r and s be defined as in (3). The theorem is obviously true if r=s=0, because then the selection of any t populations is  $\delta^*$ -correct (see the notational clarification at the end of the introductory section) yielding  $\Pr\{\delta^*$ -correct selection $\}=1$ . Thus without loss of generality, we may assume that  $r\geq 1$ . Because of (5) and (6), we only need to prove, without considering any stopping rule, that the inequality

$$Q(\vec{y}_m) \geq Q^*(\vec{y}_m)$$

holds for any possible value  $\vec{y}_m$  of  $\vec{Y}_m$  at the *m*th stage of sampling  $(m=1, 2, \cdots)$ , where  $Q^*(\vec{y}_m)$  and  $Q(\vec{y}_m)$  are given in (4) and (7), respectively. After subtracting 1 from the reciprocal of each side and rearranging the terms, we have the following equivalent inequality:

(9) 
$$\exp \{\delta^* \gamma_{\epsilon} \vec{y}_m\} (\sum_{\alpha \in S} \exp \{\vec{\tau} \cdot \alpha \vec{y}_m\}) \leq (\sum_{\gamma \in D} \exp \{\delta^* \gamma \vec{y}_m\}) (\sum_{\alpha \in T} \exp \{\vec{\tau} \cdot \alpha \vec{y}_m\})$$

where  $D=C-\{\gamma_e\}$ . To establish (9) we shall show that for every term,  $\exp{\{\delta^*\gamma_e\vec{y}_m+\vec{\tau}\cdot\alpha\vec{y}_m\}}$ , on the left-hand side, we can uniquely define an equal or larger term,  $\exp{\{\delta^*\gamma'\vec{y}_m+\vec{\tau}\cdot\alpha'\vec{y}_m\}}$ , on the right-hand side. In other words, we shall show that:

$$\delta^* \gamma_{\epsilon} \vec{y}_m + \vec{\tau} \cdot \alpha \vec{y}_m \leq \delta^* \gamma' \vec{y} + \vec{\tau} \cdot \alpha' \vec{y}_m ,$$

where  $(\alpha', \gamma') = g(\alpha)$  is the image of  $\alpha \in S$ , under an injective mapping  $g: S \rightarrow T \times D$ , to be defined below.

Consider any  $\alpha \in S$ . Let p be the total number of components which have a value >k-t, among the first r components of  $\alpha$ . If p=0, we define  $a_0=0$ ,  $b_0=k-s$ , and go to step (A) to continue our arguments therefrom. If  $p \ge 1$ , then there are p integers  $a_1, \dots, a_p$  such that

$$a_{a_i} > k - t$$
  $(i = 1, \dots, p; 1 \le a_1 < \dots < a_p \le r)$ .

Among the last t components of  $\alpha$ , there must exist a set of p smallest possible integers  $b_1, \dots, b_p$  such that

$$\alpha_{b_i} \leq k - t$$
  $(i=1,\cdots,p; k-t+1 \leq b_1 < \cdots < b_p \leq k)$ .

Step (A). Let q be the total number of components which have a value  $\leq k-t$ , among the last min  $\{s, k-b_p\}$  components of  $\alpha$ . If q=0, then we go to step (B) and continue our arguments therefrom. If  $q \ge 1$ , then there are q integers  $b_{p+1}, \dots, b_{p+q}$  such that

$$\alpha_{b_i} \leq k-t$$
  $(i=p+1,\cdots,p+q; \max\{k-s,b_p\} < b_{p+1} < \cdots < b_{p+q} \leq k)$ .

There must exist a set of q smallest possible integers  $a_{p+1}, \dots, a_{p+q}$  such that

$$a_{a_i} > k-t$$
  $(i=p+1, \dots, p+q; a_p < a_{p+1} < \dots < a_{p+q} \le k-t)$ .

Step (B). We may now define an  $\alpha' \in T$  corresponding to  $\alpha$ , in the following manner:

$$lpha_{a_i}' = lpha_{b_i}$$
,  $lpha_{b_i}' = lpha_{a_i}$ ,  $i = 1, \cdots, p+q$ ;  $lpha_j' = lpha_j$ , for all other  $j \le k$ .

Three facts may be noticed. First,  $p+q \ge 1$ , otherwise  $\alpha$  would not have been in S. Secondly, there are as many (in fact, p+q) components in  $\alpha$  which are different from those in  $\alpha'$  among the first k-tcomponents as there are among the last t components. Thirdly,  $\tau_{[b_t]}$  $\tau_{[a_i]} \geq \delta^*$  because of (3), and  $y_{[a_{a_i}]^m} \geq y_{[a_{b_i}]^m}$  because  $\alpha_{a_i} > \alpha_{b_i}$  ( $i = 1, \dots, p+q$ ).

We may further define a  $\gamma' \in D$ , corresponding to  $\alpha$ , by

(11) 
$$\gamma' = \{\gamma'_1, \dots, \gamma'_t\} = \{k-t+1, \dots, k, \alpha_{k-t+1}, \dots, \alpha_k\} - \{\alpha'_{k-t+1}, \dots, \alpha'_k\}$$
.

Thus, a mapping  $g: S \rightarrow T \times D$  has been defined by  $g(\alpha) = (\alpha', \gamma')$ . At this point, it may be profitable to give an example. Suppose k=10, t=5, r=2, and s=3. If  $\alpha=(9, 5, 6, 10, 8, 2, 3, 1, 7, 4)$ , then  $\alpha'=(2, 5, 1, 4)$ 4, 8, 9, 3, 6, 7, 10) and  $\gamma' = \{1, 2, 4, 7, 8\}.$ 

To show that g is injective, consider any  $(\alpha', \gamma')$  which is in the image set, g(S), of g. We shall find a unique  $\alpha \in S$  such that  $g(\alpha)$  $(\alpha', \gamma')$ . Hinted by (11), we have

$$\{\alpha_{k-t+1},\cdots,\alpha_k\}=\{\gamma_1',\cdots,\gamma_t',\alpha_{k-t+1}',\cdots,\alpha_k'\}-\{k-t+1,\cdots,k\}.$$

Let  $\{\alpha'_{b_i}: i=1,\dots,h; k-t+1 \leq b_1 < \dots < b_h \leq k\}$  be the set of all integers in the set  $\{\alpha'_{k-t+1}, \dots, \alpha'_k\}$  which are not found in the set  $\{\alpha_{k-t+1}, \dots, \alpha_k\}$ . Then the elements of the set

$$\{\alpha_{k-t+1}, \dots, \alpha_k\} - (\{\alpha'_{k-t+1}, \dots, \alpha'_k\} - \{\alpha'_{b_1}, \dots, \alpha'_{b_k}\})$$

must appear in the first k-t components of  $\alpha'$  with their positions identified. Suppose these are  $\alpha'_{a_1}, \dots, \alpha'_{a_h}$ ,  $(1 \le a_1 < \dots < a_h \le k-t)$ . We may now define  $\alpha$  in a unique manner:

$$egin{aligned} &lpha_{a_i}\!=\!lpha_{b_i}'\,,\quad lpha_{b_i}\!=\!lpha_{a_i}'\,,\qquad i\!=\!1,\cdots,h\;;\ &lpha_{j}\!=\!lpha_{j}'\,,\qquad \qquad & ext{for all other }j\!\leq\!\!k\,. \end{aligned}$$

Obviously  $g(\alpha) = (\alpha', \gamma')$ , and the injectiveness of g is proved. Finally, we may prove (10), which is equivalent to

$$\delta^*(\gamma_e \vec{y}_m - \gamma' \vec{y}_m) \leq \vec{\tau} \cdot (\alpha' \vec{y}_m - \alpha \vec{y}_m) ,$$

which is further equivalent to

$$\textstyle\sum_{i=1}^{p+q} (y_{[a_{a_i}]^m} - y_{[a_{b_i}]^m}) \delta^* \leq \sum_{i=1}^{p+q} (y_{[a_{a_i}]^m} - y_{[a_{b_i}]^m}) (\tau_{[b_i]} - \tau_{[a_i]}) \;.$$

Now, this last inequality is true because

$$\delta^* \leq \tau_{[b_i]} - \tau_{[a_i]} \quad \text{and} \quad 0 \leq y_{[a_{a_i}]^m} - y_{[a_{b_i}]^m} \qquad (i = 1, \cdots, p+q) \ .$$

This completes the proof.

#### 4. Discussion

The result of the theorem in the last section is interesting because (i) the experimenter need not modify his sampling procedure, but just uses  $P_B^*$ , and (ii) when  $\delta_{k-t+1,k-t} \ge \delta^*$ , result (8) automatically reduces to result (5).

A similar situation exists for the ranking problem of selecting the best t from among k normal populations, using a single-sample procedure (e.g., Bechhofer, [1]) or a two-sample procedure (Bechhofer, et al. [2]; Maurice, [5]; Ofosu, [6]). A result analogous to (8) has been obtained by Chiu [4] using entirely different mathematical techniques.

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UNIVERSITY OF HONG KONG

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## W. K. CHIU

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University of Hong Kong