BEST POPULATIONS AND TOLERANCE REGIONS(1)(2)

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1. Introduction and summary

We consider a collection of populations $\Pi = (\Pi_1, \dots, \Pi_k)$ defined over the sample space $\mathfrak{X}(\mathfrak{A})$, where \mathfrak{A} is the σ -algebra of subsets of \mathfrak{X} . We suppose there is a class of probability measures defined over $\mathfrak{X}(\mathfrak{A})$ which we designate by $\{P_x^{\theta}/\theta \in \Omega\}$. Denote the distribution function of Π_m by $P_x^{\theta_m}$, where $\theta_m \in \Omega$.

Now let $\mathfrak{b}_j = \int_A dP_x^{\theta_j}$, $\theta_j \in \Omega$ and $A \in \mathfrak{A}$. \mathfrak{b}_j is called the coverage of the set A. We now make the following

DEFINITION 1.1. A collection of populations contains a best population re the set of interest $A \in \mathfrak{A}$ if and only if there exists an ordering of the \mathfrak{b}_j such that

$$\mathfrak{b}_{[k]}\!>\!\mathfrak{b}_{[k-1]}\!\!\geq\!\mathfrak{b}_{[k-2]}\!\geq\!\cdots\!\geq\!\mathfrak{b}_{[1]}$$
 .

That is, the best population is one that gives largest coverage to the set $A \in \mathfrak{A}$.

Now it very often happens that a statistician is confronted with k populations, θ_i , $i=1,\dots,k$, unknown, and it is desirable to know, or find, or pick the "best" population (best in the sense of definition 1.1). Because of the uncertainty involved, the statistician usually settles for a procedure which will select a subset of Π in such a way that the "best" population is included in the subset with probability at least as large as a predetermined number, say P^* . (This is the philosophy of [1] and [2]). If such a procedure selects the best population, we call it a correct selection (CS), and we wish the procedure to be such that the $Pr(CS) \ge P^*$.

If in addition, the procedure used is independent of $(\theta_1, \dots, \theta_k)$, the unknown parameters involved, then we say that the procedure is parameter-free.

We examine the problem of setting parameter-free procedures for collections of normal distributions (section 2) and single exponential distributions (section 3), where A is the interval $(-\infty, a) \in R'$ and "a"

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is a constant that is known and specified beforehand.

2. Normal populations

Suppose we consider a collection of populations $\Pi = (\Pi_1, \dots, \Pi_k)$ where Π_i is distributed by $N(\mu_i, \sigma_i^2)$. We assume that there is a best population, that is, a population which has the largest value of

Now we know that $\int_{-\infty}^{t} dN(0,1)$ is a monotone increasing function of t. Hence the problem of selecting the best population is the selection of that population with

(2.2) the largest value of
$$\frac{a-\mu}{\sigma}$$

or

(2.3) the least value of
$$\frac{\mu-a}{\sigma}$$
.

This problem splits itself into various cases. To restate, we wish to pick a subset of the k populations (based on independent samples of size n independent observations from each population) in such a way that the probability of a correct selection, $\Pr(CS) \ge P^*$. We now state the procedures and give the accompanying analysis for the various cases. Case 2.1: μ 's unknown and variable; σ_i^2 known, $\sigma_i^2 = \sigma^2$, $i = 1, \dots, k$.

Examining the criterion of bestness for normal populations, that is, (2.3), we see that under condition of case 2.1, a population is best if its mean is least. We assume that for (μ_1, \dots, μ_k) , then, that there exists a best population, that is, there is a reordering of the μ 's into

Let a sample of n observations be taken independently from each population, and let \bar{X}_i denote the sample mean of the observations X_{ij} , $j=1,\dots,n$ from Π_i . We adopt the following

Procedure. Retain population Π_i in the subset if

$$(2.5) \bar{x}_{i} < \bar{x}_{(1)} + d_{1}$$

where $\bar{x}_{(1)}$ is the smallest of the k sample means \bar{x}_i , and d_1 is a constant chosen to make the probability of a correct selection at least equal to a

predetermined number, P^* . We now state the following

THEOREM 2.1: Procedure (2.5) is parameter-free.

PROOF: We must show that there exists a unique d_1 such that

- (i) $Pr(CS) \ge P^*$ for procedure (2.5), and
- (ii) d_1 is independent of (μ_1, \dots, μ_k) .

Now the $\Pr(CS) = \Pr(\bar{X} \leq \bar{X}_{(1)} + d_1)$ where \bar{X} is the sample mean computed from the best population; that is, $\Pr(CS)$

$$=\operatorname{Pr}(\bar{X}_{(1)} \geq \bar{X} - d_1)$$

$$= \int_{-\pi}^{\pi} \prod_{i=1}^{k} (1 - G(\bar{x} - d_1, \mu_{[i]}\sigma^2)) dG(\bar{x}; \mu_{[1]}, \sigma^2)$$

where

$$G(t; \mu, \sigma^2) = \int_{-\infty}^{t} \frac{\sqrt{n}}{\sqrt{2\pi}\sigma} \exp{-\frac{n}{2}\left(\frac{x-\mu}{\sigma}\right)^2 dx}.$$

Hence we have that

$$\begin{split} \Pr\left(CS\right) = & \left(\frac{\sqrt{n}}{\sqrt{2\pi}\sigma}\right)^k \int_{-\infty}^{\infty} \int_{\overline{x}-a_1}^{\infty} \cdots \int_{\overline{x}-a_1}^{\infty} \exp\left(-\frac{n}{2\sigma^2}\sum_{\frac{1}{2}}^k (\overline{x}_i - \mu_{[i]})^2\right) \\ & \cdot \exp\left(-\frac{n}{2\sigma^2}(\overline{x} - \mu_{[1]})^2 d\overline{x}_2 \cdots d\overline{x}_k d\overline{x} \right) \\ = & \left(\frac{\sqrt{n}}{\sqrt{2\pi}\sigma}\right)^k \int_{-\infty}^{\infty} \int_{\overline{x}-a_1-\mu_{[k]}}^{\infty} \cdots \int_{\overline{x}-a_1-\mu_{[2]}}^{\infty} \exp\left(-\frac{n}{2\sigma^2}\sum_{\frac{1}{2}}^k t_i^2\right) \\ & \cdot \exp\left(-\frac{n}{2\sigma^2}(\overline{x} - \mu_{[1]})^2 dt_2 \cdots dt_k d\overline{x} \right). \end{split}$$

We let $\bar{x} - \mu_{[1]} = t_1$, and we then have that the

$$\begin{aligned} \Pr\left(CS\right) &= \left(\frac{\sqrt{n}}{\sqrt{2\pi}\sigma}\right)^k \int_{-\infty}^{\infty} \int_{t_1 - d_1 + \mu_{[1]} - \mu_{[k]}}^{\infty} \cdots \int_{t_1 - d_1 + \mu_{[1]} - \mu_{[2]}}^{\infty} \\ &= \exp{-\frac{n}{2\sigma^2} \sum_{1}^{k} \mathbf{t}_i^2 dt_2 \cdots dt_k dt_1} = H_{d_1}(\mu_{[1]} - \mu_{[k]}, \cdots, \mu_{[1]} - \mu_{[2]}). \end{aligned}$$

An examination of H_{a_1} shows it is a monotone decreasing function in its arguments. Further, if we fix $\mu_{[1]}$, and bearing in mind (2.4), we note that H_{a_1} is minimized for a choice of $\mu_{[2]}$ if we set $\mu_{[2]}$ so close to $\mu_{[1]}$ that for all purposes $\mu_{[2]} = \mu_{[1]}$. Similarly, H_{a_1} is minimized over a choice of $\mu_{[3]}$ if we set $\mu_{[3]} = \mu_{[2]} = \mu_{[1]}$, and finally, H_{a_1} is minimized if

$$\mu_{[1]} = \mu_{[2]} = \cdots = \mu_{[k]}$$
.

That is, the minimum value of H_{a_1} is $H_{a_1}(0, \dots, 0)$. Now $H_{a_1}(0, \dots, 0)$ when regarded as a function of d_1 , is continuous and monotone increasing. Hence if we let

$$(2.7) P^* = H_{a_1}(0, \dots, 0)$$

we may solve for d_1 and obtain a unique d_1 which satisfies (2.7), and because $H_{a_1}(0,\dots,0)$ is the minimum value of H, then for the "true configuration" (2.4), we have

$$\Pr(CS) \ge P^*$$

where d_1 is determined from (2.7), and is thus independent of $(\mu_{[1]}, \dots, \mu_{[k]})$. Hence, the theorem is proved.

Case 2.2: μ 's unknown and variable; σ^2 's known and variable.

Let $\delta_i' = (\mu_i - a)/\sigma_i$, and denote the ordered δ_i' (under the assumption that there is a best population in Π) by

$$\delta'_{[1]} < \delta'_{[2]} \leq \delta'_{[3]} \leq \cdots \leq \delta'_{[k]}$$

We seek to establish a procedure that will choose a subset of Π which contains that population that has $\delta_i' = \delta'_{[1]}$. Let a sample of n independent observations be taken independently from each population, and let \bar{X}_i be the sample mean of the observations taken from Π_i . We let

$$z_i' = \frac{\overline{x}_i - a}{\sigma_i}$$

and denote the ordered $z_{i'}$ by

$$z'_{(1)} < z'_{(2)} < \cdots < z'_{(k)}$$
.

We adopt the following

Procedure. Retain population Π_i in the subset if

$$(2.8) z_i' < z_{(1)}' + d_2$$

where d_2 is a constant chosen to make the $Pr(CS) \ge P^*$. We now state and prove the following

THEOREM 2.2: Procedure (2.8) is parameter-free.

PROOF: We have that the $\Pr(CS) = \Pr(z' < z'_{(1)} + d_2)$ where z' is computed from the population with $\delta' = \delta'_{(1)}$. Now the

$$\Pr(CS) = \Pr(\sqrt{n} \ z' < \sqrt{n} \ z'_{(1)} + \sqrt{n} \ d_2)$$
$$= \Pr(z < z_{(1)} + d_2')$$

where we let \sqrt{n} z'=z, \sqrt{n} $z'_{(1)}=z_{(1)}$ and \sqrt{n} $d_2=d_2'$, and we will let \sqrt{n} $\delta'_i=\delta_i$.

Hence the

$$\begin{aligned} \Pr\left(CS\right) &= \Pr\left(z_{(1)} > z - d_{2}'\right) \\ &= \int_{-\infty}^{\infty} \prod_{i=2}^{k} \left(1 - G^{(1)}(z - d_{2}'; \, \delta_{[i]})\right) \; dG^{(1)}(z, \, \delta_{[1]}) \end{aligned}$$

where

$$G^{(1)}(t;\delta) = \int_{-\infty}^{t} \frac{1}{\sqrt{2\pi}} \exp{-\frac{1}{2}(x-\delta)^2} dx;$$

that is,

$$\begin{split} \Pr\left(CS\right) = & \int_{-\infty}^{\infty} \int_{s-d_{2}'}^{\infty} \cdots \int_{s-d_{2}'}^{\infty} \left[\prod_{2}^{k} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} (z_{i} - \delta_{[i]})^{2}\right) \right] \\ & \cdot \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} (z - \delta_{[1]})^{2} dz_{2} \cdots dz_{k} dz \right) \\ = & \int_{-\infty}^{\infty} \int_{s-d_{2}' - \delta_{[k]}}^{\infty} \cdots \int_{s-d_{2}' - \delta_{[2]}}^{\infty} \left[\prod_{2}^{k} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} t_{i}^{2}\right) \right] \\ & \cdot \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} (z - \delta_{[1]})^{2} dt_{2} \cdots dt_{k} dz \right). \end{split}$$

Now set $z-\delta_{[1]}=t_1$, that is, $z=t_{(1)}+\delta_{[1]}$. Then the

$$\begin{split} \Pr\left(CS\right) = & \int_{-\infty}^{\infty} \int_{t_{1}-d_{2}'+\delta_{[1]}-\delta_{[k]}}^{\infty} \cdots \\ & \cdot \int_{t_{1}-d_{2}'+\delta_{[1]}-\delta_{[2]}}^{\infty} \left[\prod_{i=1}^{k} \frac{1}{\sqrt{2\pi}} \exp{-\frac{1}{2} t_{i}^{2}} \right] dt_{2} \cdots dt_{k} dt_{1} \\ = & H'_{d_{2}'}(\delta_{[1]} - \delta_{[k]}, \cdots, \delta_{[1]} - \delta_{[2]}) \ . \end{split}$$

As in Theorem 2.1, it can be shown that the minimum value of H'_{d_2} is $H'_{d_2}(0,0,\cdots,0)$ and that there exists a unique d'_2 for which

$$P^* = H'_{d_2'}(0, \dots, 0)$$
.

Hence the theorem is proved, and we may use procedure (2.8) to pick a subset containing the best population with confidence at least P^* , and where $d_2' = \sqrt{n} \ d_2$.

Case 2.3: μ 's unknown and variable, σ_i^2 unknown, $\sigma_i^2 \equiv \sigma^2$.

It is clear from the criterion (2.3) that here again we wish to retain in our subset that population with the smallest μ . However, we do not

know the common value σ^2 of the σ_i^2 , and so we use as an estimate the pooled sample variance S^2 , where

(2.9)
$$S^{2} = \frac{(n-1)s_{1}^{2} + \cdots + (n-1)s_{k}^{2}}{k(n-1)} = \frac{1}{k} \sum_{i=1}^{k} s_{i}^{2}$$

where

$$S_i^2 = \frac{1}{n-1} \sum_{j=1}^n (X_{ij} - \bar{X}_i)^2,$$
 $j = 1, \dots, n \text{ and } i = 1, \dots, k.$

 $k(n-1)(S^2/\sigma^2)$ is of course a χ^2 -variable with $k(n-1)=\gamma$ degrees of freedom. For this case, we use the following

Procedure. Retain population Π_i if

$$(2.10) \bar{x}_i \leq \bar{x}_{(1)} + d_3 S$$

where, as usual $\bar{x}_{(1)}$ is the smallest of the \bar{x}_i , and d_3 is a constant chosen to make the $\Pr(CS) \geq P^*$. We now state the following:

THEOREM 2.3: Procedure (2.10) is parameter-free.

PROOF: We have that the $\Pr(CS) = \Pr(\bar{x} \leq \bar{x}_{(1)} + d_3S)$ where \bar{x} is the sample mean computed from $N(\mu_{(1)}, \sigma^2)$. Now the

$$\begin{aligned} \Pr(CS) &= \Pr(\overline{x}_{(1)} \geq \overline{x} - d_3 S) \\ &= \Pr(\overline{x}_{(1)} - \mu_{[1]} \geq \overline{x} - \mu_{[1]} - d_3 S) \\ &= \Pr\left(\frac{\overline{x}_{(1)} - \mu_{[1]}}{S} > \frac{\overline{x} - \mu_{[1]}}{S} - d_3\right) \\ &= \int_{-\infty}^{\infty} \left[\prod_{j=3}^{k} \left(1 - T(t' - d_3; \, \delta_{[j]}) \right] dT(t'; \, \delta = 0) \right] \end{aligned}$$

where $t' = (\bar{x} - \mu_{11})/S$ and is a Student t/\sqrt{n} variable with $\gamma = k(n-1)$ degrees of freedom.

$$\begin{split} \delta_{[j]} = & \frac{\sqrt{n}}{\sigma} \left[\mu_{[j]} - \mu_{[1]} \right], \\ 1 - T(t' - d_3; \, \delta_{[j]}) = & \int_{t' - d_3}^{\infty} f(t'_j; \, \delta_{[j]}) dt'_j, \end{split}$$

and $f(t_j', \delta_{[j]})$ is the probability density function of the noncentral t/\sqrt{n} variable, noncentrality parameter $\delta_{[j]}$ with $\gamma = k(n-1)$ degrees of freedom, and $T(t', \delta = 0)$ is the Student t/\sqrt{n} distribution with γ degrees of freedom given by

$$\int_{-\infty}^{t'} \frac{\sqrt{n}}{\sqrt{\pi \gamma}} \frac{\Gamma((\gamma+1)/2)}{\Gamma(\gamma/2)} \frac{1}{\{1+(n\nu^2/\gamma)\}^{(\gamma+1)/2}} \, d\nu \ .$$

Since we have the ordering of the μ 's, viz

$$\mu_{\scriptscriptstyle{[1]}} < \mu_{\scriptscriptstyle{[2]}} \leq \cdots \leq \mu_{\scriptscriptstyle{[k]}}$$

note that this induces an ordering of the δ 's, viz

$$(2.12) 0 < \delta_{[2]} \leq \delta_{[3]} \cdot \cdots \leq \delta_{[k]}.$$

Now it is well known that $1-T(\omega, \delta)$ is an increasing function of its non-centrality parameter δ . To see this, let X denote an N(0,1) variable. Then by definition of a non-central t/\sqrt{n} variable, we have that

$$\begin{aligned} 1 - T(\omega; \, \delta) &= \Pr\left(\frac{1}{\sqrt{n}} \frac{X + \delta}{S'} \ge \omega\right) = \Pr\left(\frac{X + \delta}{S} \ge \sqrt{n} \, \omega\right) \\ &= \Pr\left(X \ge \sqrt{n} \, \omega S - \delta\right). \end{aligned}$$

As δ increases, the region $[(X,S)|X \ge \sqrt{n}\omega S - \delta]$ expands, that is, more and more of the probability measure over the half plane $[(X,S)|-\infty < X < \infty, 0 < S < \infty]$ is included, and hence $1-T(\omega,\delta)$ increases as δ increases. Now noting the definition of the $\delta_{[j]}$, $j=2,\cdots,k$ and the condition (2.12), we see that the quantity (2.11) attains its minimum if the $\delta_{[j]}$ are zero. (The $\delta_{[j]}$ are never negative since $\mu_{[j]} > \mu_{[1]}$). That is, the minimum value of (2.11), is

$$\int_{-\infty}^{\infty} \prod_{i=2}^{k} (1 - T(t' - d_3; \delta = 0)) \ dT(t'; \delta = 0)$$

where $T(t; \delta=0)$ is given above. Note that this is a continuous function of d_3 , and monotone increasing in d_3 , and hence by similar arguments to the above theorems, this theorem is proved, and we can always use procedure (2.10) to select a subset containing the best population under Case 2.3, with confidence at least P^* .

Case 2.4: μ 's known, with $\mu_i \equiv \mu$, $i=1,\dots,k$; σ^2 's unknown and variable.

We discuss the case $\mu > a$. Because we are interested in the population with the least value of $(\mu - a)/\sigma_i$, Case 2.4, and the assumption $\mu > a$ implies that we are looking for that population with the largest of the σ_i . Suppose the ordered σ 's are

(2.13)
$$\sigma_{[1]}^2 \leq \sigma_{[2]}^2 \leq \cdots \leq \sigma_{[k-1]}^2 < \sigma_{[k]}^2$$

that is, there exists a best population in the sense of Definition 1.1. Suppose again that independent samples of n independent observations, X_{ij} are taken, where $i=1,\dots,k;\ j=1,\dots,n$. Let

$$(2.14) v_i^2 = \frac{1}{n} \sum_{j=1}^{n} (X_{ij} - \mu)^2.$$

Let $v_{(1)}^2 < \cdots < v_{(k)}^2$ be the ordered v_i^2 's. We use the following Procedure. Retain Π_i in the subset if

$$(2.15) v_i^2 \ge d_i v_{(k)}^2$$

where d_4 is a constant such that $0 < d_4 < 1$, and is chosen so that the $Pr(CS) \ge P^*$. Again, we may state the following

THEOREM 2.4: Procedure (2.15) is parameter-free.

PROOF: We have that the $\Pr(CS) = \Pr(v^2 \ge d_4 v_{(k)}^2)$ where v^2 is the sample variance defined in (2.14) computed from the best population. That is, the

$$egin{aligned} &\operatorname{Pr}\left(CS
ight) \!=\! \operatorname{Pr}\left(v_{\scriptscriptstyle(k)}^2 \!\leq\! rac{v^2}{d_4}
ight) \ &= \! \int_{\scriptscriptstyle 0}^{\scriptscriptstyle \infty} \! \left[\prod_{\scriptscriptstyle i=1}^{k-1} C\!\left(rac{v^2}{d_i}; \, \sigma_{\scriptscriptstyle [i]}^2
ight)
ight] dC(v^2; \,\, \sigma_{\scriptscriptstyle [k]}^2) \end{aligned}$$

where

$$C(v^2; \ \sigma_{[i]}^2) = \int_0^{v^2} \frac{1}{\Gamma(n/2)} \frac{n^{n/2}}{(2\sigma_1^2)^{n/2}} \exp \frac{-nv_i^2}{2\sigma_{[i]}^2} (v_i^2)^{(n/2)-1} \ dv_i^2 \ .$$

Hence we may see that the

$$\begin{split} \Pr(CS) = & \int_{0}^{\infty} \int_{0}^{(\omega_{k}^{2}/d_{4})(\sigma_{[k]}^{2}/\sigma_{[k-1]}^{2})} \cdots \int_{0}^{(\omega_{k}^{2}/d_{4})(\sigma_{[k]}^{2}/\sigma_{[1]}^{2})} \cdots \left[\prod_{i=1}^{k} \frac{n^{n/2}}{\Gamma(n/2)2^{n/2}} (\omega_{i}^{2})^{(n/2)-1} \right. \\ & \cdot \exp \frac{-n\omega_{i}^{2}}{2} \right] \! d\omega_{1}^{2} \cdots d\omega_{k-1}^{2} d\omega_{k}^{2} \\ = & K_{d_{4}} \! \left(\frac{\sigma_{[k]}^{2}}{\sigma_{[k-1]}^{2}}, \cdots, \frac{\sigma_{[k]}^{2}}{\sigma_{[1]}^{2}} \right). \end{split}$$

Now K_{a_4} is a monotone increasing function in its arguments, subject to (2.13). It is obvious that the minimum value of K_{a_4} is K_{a_4} $(1,\dots,1)$ and hence if we set $K_{a_4}(1,\dots,1)=P^*$ we may find a unique d_4 which makes

$$\Pr(CS) \ge P^*$$

and the procedure (2.15) is parameter-free.

(It should be pointed out that if one analyzes the case $\mu < a$, best population is that population with the least σ^2 , and that one may verify that the

Procedure. Retain Π_i if

$$(2.15) v_i^2 \leq d_i' v_{(1)}^2 ,$$

is parameter-free, where $v_{(1)}^2$ is the smallest of the v_i^2 's defined in (2.14), and d_4' is a constant chosen to make the $\Pr(CS) \ge P^*$. In fact it can be shown that the

$$\begin{split} \Pr(CS) = & \int_{0}^{\infty} \int_{(\omega_{1}^{2}/a'_{4})(\sigma_{1}^{2})/\sigma_{1}^{2}}^{\infty} \cdots \int_{(\omega_{1}^{2}\sigma_{1}^{2})/a'_{4}\sigma_{1}^{2})}^{\infty} \left[\prod_{i=1}^{k} \frac{n^{n/2}}{2^{n/2}\Gamma(n/2)} (\omega_{i}^{2})^{(n/2)-1} \right. \\ & \cdot \exp \left. \frac{-n\omega_{i}^{2}}{2} \right] d\omega_{2}^{2} \cdots d\omega_{k}^{2} d\omega_{1}^{2} = K'_{d'_{4}} \left(\frac{\sigma_{11}^{2}}{\sigma_{1k1}^{2}}, \cdots, \frac{\sigma_{11}^{2}}{\sigma_{12}^{2}} \right) \end{split}$$

where under the assumption of the existence of a best population in we have

$$\sigma_{[1]}^2 < \sigma_{[2]}^2 \leq \cdots \leq \sigma_{[k]}^2$$

and hence that the

$$\Pr(CS) \geq K'_{d'}(1,\dots,1)$$
.

On setting the right hand member of the above inequality to P^* , we obtain a unique d_4 satisfying $K'_{a'_4}(1,\dots,1)=P^*$, and hence (2.15) is parameter-free).

Case 2.5: μ 's known, variable; σ 's unknown and variable.

Again, let us assume that we have a collection of normal populations Π_i , and that they are distributed by the $N(\mu_i, \sigma_i^2)$ distribution. Bearing in mind the condition of Case 2.5, and that we seek to find that population with least $(\mu_i - a)/\sigma_i$, it is readily seen that this case splits into the following three cases.

- Case 2.5 (a) All μ_i known and less than a
 - (b) All μ_i known and greater than a
 - (c) All μ_i known, with $\mu_{[1]} < \mu_{[2]} < \cdots < \mu_{[k_1]} < a$, and $a < \mu_{[k_1+1]} < \cdots < \mu_{[k]}$ where $1 < k_1 < k$.

The case (2.5a) will be readily seen to be symmetric and analogous to case (2.5b). Further, if for a normal distribution, the population mean

is such that $\mu > a$, then the coverage of $(-\infty, a)$ is less than $\frac{1}{2}$. That is, for the case (2.5c), we can disregard those populations Π_j with $a < \mu_j$, and formulate a procedure for selecting the best population out of the remaining k_1 populations (that have their means $\mu < a$). Of course, this will be the same solution for case (2.5a). Note that $k_1 > 1$ for if $k_1 = 1$, then automatically we know the best population.

We now discuss, then, the problem of finding the best normal population of a collection $\Pi = (\Pi_1, \dots, \Pi_k)$ of normal populations, where the means are known, and $\mu_i < a$, $i = 1, \dots, k$, and where best population implies, as we have seen, the population with the largest $(a - \mu_i)/\sigma_i$. That is, we wish to select a subset of Π in such a way that the population with the smallest $\sigma_i/(a - \mu_i)$ is retained in our subset, with probability of this correct selection at least P^* .

Using the notation of the previous cases, let

$$v_i^2 = \frac{1}{n} \sum_{j=1}^{n} (X_{ij} - \mu_i)^2$$
 $i = 1, \dots, k$

be the unbiased estimate of σ_i^2 . Let

$$q_i = \frac{v_i}{a - \mu_i}$$

and denote the ordered q_i 's by

$$q_{(1)} < q_{(2)} < \cdots < q_{(k)}$$

We now state the following

Procedure. Retain Π_i if

$$q_i \leq d_b \, q_{\scriptscriptstyle (1)}$$

where $d_{\mathfrak{s}}$ is a constant chosen to make the $\Pr(CS) \geq P^*$, and is such that $1 < d_{\mathfrak{s}}$. We now prove the following

THEOREM 2.5: Produre (2.17) is parameter-free.

PROOF: We have that the $\Pr(CS) = \Pr(q \le d_i q_{(1)})$, where q denotes that q_i which is computed from the population having smallest $\sigma_i/a - \mu_i$, that is, the best population.

Let $\delta_i = \frac{\sigma_i}{a - \mu_i}$ and denote the ranked δ 's by

$$(2.18) \delta_{[i]} < \delta_{[a]} \leq \delta_{[a]} \leq \cdots \leq \delta_{[k]}.$$

Then we have that

$$\begin{split} \Pr\left(CS\right) &= P\!\!\left(q_{\scriptscriptstyle(1)} \! \ge \! \frac{q}{d_{\scriptscriptstyle 5}}\right) \\ &= \! \int_{\scriptscriptstyle 0}^{\scriptscriptstyle \infty} \left[\prod_{i=2}^{k} \left(1 \! - \! M\!\!\left(\frac{q}{d_{\scriptscriptstyle 5}}; \; \delta_{\scriptscriptstyle [i]}\right)\right)\right] dM\!\left(q; \; \delta_{\scriptscriptstyle [1]}\right) \end{split}$$

where

$$1 - M(q/d_{5}; \delta_{[i]}) = \int_{q/d_{5}}^{\infty} \frac{1}{\delta_{[i]} 2^{(n/2)-1} \Gamma(\frac{n}{2})} \left(\frac{q_{i}}{\delta_{[i]}}\right)^{n-1} e^{-\delta_{i}^{2}/2\delta_{[i]}^{2}} dq_{i}.$$

By using procedures similar to the above, we may verify that the

$$egin{aligned} \Pr\left(CS
ight) = & \int_{0}^{\infty} \int_{(\omega_{1}/a_{8})(\delta_{[1]}/\delta_{[k]})}^{\infty} \cdots \int_{(\omega_{1}/a_{5})(\delta_{[1]}/\delta_{[2]})}^{\infty} \left[\prod_{i=1}^{k} rac{e^{-\omega_{i}^{2}/2} \omega_{i}^{n-1}}{2^{(n/2)-1} \Gamma\left(rac{n}{2}
ight)}
ight] d\omega_{2} \cdots d\omega_{k} \ d\omega_{1} \ = & U_{a_{5}}\!\!\left(rac{\delta_{[1]}}{\delta_{[k]}}, \cdots, rac{\delta_{[1]}}{\delta_{[2]}}
ight). \end{aligned}$$

An examination of U_{a_5} shows it is a monotone decreasing function of its arguments, subject to (2.18). It is easy to see that U_{a_5} has minimum value

$$U_{d_s}(1,\cdots,1)$$

that is, the minimum value occurs when

$$\delta_{[1]} = \delta_{[2]} = \cdots = \delta_{[k]}$$
.

Note that $U_{a_5}(1,\dots,1)$ is a continuous and monotone increasing function of d_5 . Hence there exists a unique d_5 which satisfies

$$U_{a_5}(1,\cdots,1)=P^*$$

and for this unique $d_{\mathfrak{s}}$,

$$\Pr(CS) \geq U_{a_5}(1,\cdots,1) = P^*$$

that is, procedure (2.17) is parameter-free.

(It should be pointed out that for the case (2.5b), that under the assumption of the existence of a best population, we wish to retain the population with largest value of $\delta'_i = \sigma_i/(\mu_i - a)$. We let $q_i' = v_i/(\mu_i - a)$ and it can be verified that the

Procedure. Retain population Π_i if

$$(2.19) q_i' > d_i' q_{(k)}'$$

where $q'_{(k)} = \max_{i=1}^k q'_i$, and d'_5 is a constant, $0 < d'_5 < 1$, such that the $\Pr(CS) \ge P^*$, is parameter-free. In fact, the

$$\begin{split} \Pr(CS) = & \int_{0}^{\infty} \int_{0}^{(\omega_{k}/d_{b}')(\delta_{[k]}'/\delta_{[k-1]}')} \cdots \int_{0}^{(\omega_{k}/d_{b}')/(\delta_{[k]}'/(\delta_{[1]}')} \left[\prod_{i=1}^{k} \frac{e^{(-\omega_{i}^{2}/2)} \omega_{i}^{n-1}}{2^{(n/2)-1} \Gamma(n/2)} \right] \\ & \cdot d\omega_{i} \cdots d\omega_{k-1} d\omega_{k} \\ = & U'_{d_{b}'} \left(\frac{\delta_{[k]}'}{\delta_{[k-1]}'}, \cdots, \frac{\delta_{[k]}'}{\delta_{[1]}'} \right). \end{split}$$

It is easy to see that the minimum value of U'_{d_5} is $U'_{d_5}(1,\dots,1)$ and setting this equal to the desired P^* , gives a unique d'_5 , independent of the δ'_i and hence (2.19) is parameter-free.

3. Exponential populations

We turn now to the situation where our collection Π of k populations is exponentially distributed, that is, the probability density function of the ith population Π_i is

(3.1)
$$\frac{1}{\sigma_i} \exp{-\frac{1}{\sigma_i} (x - \mu_i)} \qquad x \ge \mu_i, \ \sigma_i > 0$$
 otherwise

We again assume that the set of interest is $A=(-\infty,a)$, where "a" is a known constant. As in the normal cases discussed above, we assume in the sequel that there always exist a best population in the sense of Definition 1.1 in the collection. Again, as in the normal cases, the best population is that with the largest value of $(a-\mu)/\sigma$. We discuss the following cases.

Case 3.1: μ 's known, $\mu_i \equiv \mu$, $i=1,\dots,k$; σ_i 's unknown and variable.

If the known value of μ is such that $\mu < a$, it is clear that the best population is that with least σ . If $\mu > a$, the exponential distribution whose density is defined in (3.1), gives zero coverage to $(-\infty, a)$ and hence there would not be a best population re this set of interest in the collection Π , contrary to assumption, and we thus disregard this problem.

We now assume, then, that $\mu < a$, and let k independent samples of n independent observations be taken, and let $Y_{ij} = X_{ij} - \mu$. The Y_{ij} have density functions

We adopt the following

Procedure. Retain Π_i if

$$(3.3)$$
 $\bar{y}_{i} < f_{1} \bar{y}_{(1)}$

where $\bar{y}_i = n^{-1} \sum_{j=1}^n Y_{ij}$, $\bar{y}_{(1)}$ is the smallest of the \bar{y}_i , and f_1 is a constant chosen to make the $\Pr(CS) \ge P^*$.

THEOREM 3.1: Procedure (3.3) is parameter-free.

PROOF: It is straightforward to show that the

$$\Pr(CS) = \int_{0}^{\infty} \int_{(t_{1}/f_{1})(\sigma_{[1]}/\sigma_{[k]})}^{\infty} \cdots \int_{(t_{1}/f_{1})(\sigma_{[1]}/\sigma_{[2]})}^{\infty} \left[\prod_{i=1}^{k} \frac{n^{n}}{\Gamma(n)} e^{-nt_{i}} t_{i}^{n-1} \right] dt_{2} \cdots dt_{k} dt_{1} \\
= V_{f_{1}} \left[\frac{\sigma_{[1]}}{\sigma_{[k]}}, \cdots, \frac{\sigma_{[1]}}{\sigma_{[n]}} \right].$$

An examination of V_{f_1} shows it is a monotone decreasing function of its arguments, subject to

$$(3.4) \sigma_{\scriptscriptstyle [1]} < \sigma_{\scriptscriptstyle [2]} \le \cdots \le \sigma_{\scriptscriptstyle [k]}.$$

Hence the $\Pr(CS) \ge V_{f_1}(1,\dots,1)$. But V_{f_1} is a monotone increasing function and continuous in f_1 , and thus there exists a unique f_1 such that $V_{f_1}(1,\dots,1) = P^*$, and which is clearly independent of the parameters $\sigma_{[i]}$, that is, (3.3) is parameter-free and its use enables us to make a correct selection with $\Pr(CS)P \ge P^*$.

Case 3.2: μ 's unknown and variable, $\sigma_i \equiv \sigma$, $i=1,\dots,k$ and known.

We assume that there is a best population, that is, there is at least one of the $k \Pi_i$ having $\mu_i < a$.

Let $t_i = x_{(1)}^i = \min_{j=1}^n x_{ij}$, and let $t_{(1)}, \dots, t_{(k)}$ be the ordered t_i 's. Note that the best population is the one with the least μ . Hence we adopt the following

Procedure. Retain Π_i if

$$(3.5) t_{i} \leq t_{(1)} + f_{2}$$

where f_2 is a constant chosen to make the $Pr(CS) \ge P^*$.

THEOREM 3.2: Procedure (3.5) is parameter-free.

PROOF: It is straight forward to verify that the

$$\begin{split} \Pr(CS) = & \int_{0}^{\infty} \int_{\omega_{1} - f_{2} + \mu_{[1]} - \mu_{[k]}}^{\infty} \cdots \int_{\omega_{1} - f_{2} + \mu_{[1]} - \mu_{[2]}}^{\infty} \left[\prod_{i=1}^{k} \frac{n}{\sigma} e^{-n\omega_{i}/\sigma} \right] d\omega_{2} \cdots d\omega_{k} \ d\omega_{1} \\ = & W_{f_{2}}(\mu_{[11} - \mu_{[k]}, \cdots, \mu_{[11} - \mu_{[2]})) \end{split}$$

where $\mu_{[1]} < \mu_{[2]} \le \cdots \le \mu_{[k]}$. Hence the $\Pr(CS) \ge W_{f_2}(0, \cdots, 0)$ and if we set $W_{f_2}(0, \cdots, 0) = P^*$, there exists a unique f_2 satisfying this latter equation, independent of the μ 's, and hence parameter-free, with the $\Pr(CS) \ge P^*$.

Case 3.3: μ 's unknown, variable; σ_i 's known and variable.

We again assume that there is a best population, that is, at least one of the $k \Pi_i$ have $\mu_i < a$. Let $\delta_i = (\mu_i - a)/\sigma_i$ and let the ordered δ 's be denoted by

$$(3.6) \delta_{[1]} < \delta_{[2]} \leq \delta_{[3]} \leq \cdots \leq \delta_{[k]}.$$

Clearly we wish to select the population with its $\delta = \delta_{[1]}$. Now let

$$X_{(1)}^{i} = \min_{i=1}^{n} X_{i,i}$$
 $i=1,\dots,k$

let $Z_i = (X_{(1)}^i - a)/\sigma_i$. We adopt the following

Procedure. Retain Π_i if

$$(3.7) Z_{i} \leq Z_{(1)} + f_{3}$$

where $Z_{(1)}$ is the smallest of the Z_i and f_3 is a constant chosen to make the $Pr(CS) \ge P^*$. We now state the following

THEOREM 3.3: Procedure (3.7) is parameter-free.

PROOF: Using the same analysis as in the previous cases, it is readily verified that the

$$\begin{split} \Pr(CS) = & \int_{0}^{\infty} \int_{\omega_{1} - f_{3} + \delta_{[1]} - \delta_{[k]}}^{\infty} \cdots \int_{\omega_{1} - f_{3} + \delta_{[1]} - \delta_{[2]}}^{\infty} \left[\prod_{1}^{k} n \, e^{-n\omega_{k}} \right] d\omega_{2} \cdots d\omega_{k} \, d\omega_{1} \\ = & L_{f_{3}}(\delta_{[1]} - \delta_{[k]}, \, \cdots, \, \delta_{[1]} - \delta_{[2]}) \end{split}$$

where the δ 's are subject to (3.6). The minimum value of L_{f_3} is $L_{f_3}(0,\dots,0)$ and if we set $L_{f_3}(0,\dots,0)=P^*$, there exists a unique f_3 satisfying this latter equation and independent of the μ_i and σ_i ; that is, procedure (3.7) is parameter-free and is such that the $\Pr(CS) \geq P^*$.

Case 3.4: μ 's known and variable, σ 's unknown and variable.

This case splits itself into the following cases;

Case 3.4(a) All μ_i known and such that $\mu_i < a$, $i=1, \dots, k$.

Case 3.4(b) All μ_i known and such that $\mu_i > a$, $i=1, \dots, k$.

Case 3.4(c) All μ_i known with $\mu_{[1]} < \cdots < \mu_{[k_1]} < a$ and $a < \mu_{[k_1+1]} < \cdots < \mu_{[k]}$, where $1 < k_1 < k$.

Case (3.4b) can obviously be disregarded since for the exponential distribution as defined by (3.1), the coverage of $(-\infty, a)$ is zero if $\mu_i > a$. Case (3.4c), then, is such that we can immediately disregard the $k-k_1$ populations which are such that their $\mu_i > a$, and use a procedure to find the best population of the remaining k_1 populations which are such that their $\mu_i < a$. Of course, this is case (3.4a) with k_1 replaced by k. Note that $k_1 > 1$, for if $k_1 = 1$, we automatically know the best population. We therefore formulate a procedure for case (3.4a), which can be used if case (3.4c) obtains.

Let k independent samples of n independent observations be taken, and let $(X_{(1)}^i, \dots, X_{(n)}^i)$ denote the n ordered observations from population Π_i .

Define $S_i = (n-1)^{-1} \sum_{j=1}^{n} (X_{(j)}^i - X_{(1)}^i)$. To restate, we wish to find that population with the largest value of $(a-\mu_i)/\sigma_i$, where the μ_i are known and less than a, and thus we wish to find the population with the least value of $\delta_i = \sigma_i/(a-\mu_i)$. We let

$$(3.8) \delta_{[1]} < \delta_{[2]} \le \cdots \le \delta_{[k]}$$

denote the ordered δ_i 's.

Let $z_i=s_i/(a-\mu_i)$ and let $z_{(1)}< z_{(2)}< \cdots < z_{(k)}$ denote the ordered z_i 's. We now formulate the following

Procedure. Retain Π_i if

$$(3.9) z_i \leq f_i z_{(1)}$$

where f_4 is a constant chosen to make the $Pr(CS) \ge P^*$.

THEOREM 3.4: Procedure (3.9) is parameter-free.

PROOF: Since the probability density function of z_i is given by

$$\frac{(n-1)^{n-1}}{\delta_i^{n-1}\Gamma(n-1)}z_i^{n-2}\exp\{-(n-1)z_i/\delta_i\}\ dz_i$$

it is easy to see that the Pr(CS) is given by

$$\begin{split} \Pr(CS) = & \int_{0}^{\infty} \int_{(\omega_{1}/f_{4})(\delta_{[1]}/\delta_{[k]})}^{\infty} \cdots \int_{(\omega_{1}/f_{4})(\delta_{[1]}/\delta_{[2]})}^{\infty} \left[\prod_{i=1}^{k} \frac{(n-1)^{n-1}}{\Gamma(n-1)} \, \omega_{i}^{n-2} \, e^{-(n-1)\omega_{i}} \right] \\ & \cdot d\omega_{2} \cdots d\omega_{k} \, d\omega_{1} \\ = & M_{f_{4}} \left(\frac{\delta_{[1]}}{\delta_{[k]}}, \, \cdots, \, \frac{\delta_{[1]}}{\delta_{[2]}} \right) \end{split}$$

where $\delta_{[1]} < \delta_{[2]} \le \cdots \le \delta_{[k]}$. M_{f_4} is a monotone decreasing function in its arguments, and hence

$$\Pr(CS) \geq M_{f_A}(1, \dots, 1)$$
.

If we set $M_{f_4}(1, \dots, 1) = P^*$, and because the function $M_{f_4}(1, \dots, 1)$ we see that there exists a unique f_4 satisfying this last equation, and is independent of the parameters δ_i , that is, the procedure (3.9) is parameter-free and such that the $\Pr(CS) \geq P^*$.

Case 3.5: μ 's unknown and variable; σ_i unknown, $\sigma_i = \sigma$.

Before analyzing this case, we discuss an analogue of the Student-t variable, to be denoted by the symbol U_v , and called the central U-variable with v degrees of freedom. We denote the exponential distribution by $E(\mu_i, \sigma_i)$, whose density function is given by expression (3.1).

Now let Y be a random variable which is distributed as a $\gamma(v)/v$ variables, that is, Y has the density function

$$\frac{V^{\circ}}{\Gamma(v)} y^{v-1} e^{-vy} dy \qquad y \ge 0$$

$$0 \qquad \text{otherwise.}$$

Further, let W be an E(0,1) variable, and suppose that W and Y are independent. Define $U_v = W/Y$, and it is easy to see that the distribution of U has the density function given by

(3.11)
$$\begin{cases} \frac{du}{[1+(U/v)]^{v+1}} & \text{if } U > 0 \\ 0 & \text{otherwise.} \end{cases}$$

We define $U_v^1=(W+\delta)/Y$, to be called the non-central U variable, noncentrality parameter δ , with v degrees of freedom. Although we do not derive its density, we note that its "anti-cumulative,"

(3.12)
$$1 - H(C; \delta) = \Pr(U_v^1 \ge C)$$

is an increasing function of δ , for this is the

$$\Pr(W > CY - \delta)$$

and as δ increases, more and more of the probability measure over the region $\{(W, Y)|0 < W, Y < \infty\}$ is included.

Now suppose we take k independent samples of n observations and let $(X_{(1)}^i, \dots, X_{(n)}^i)$ be the ordered observations from Π_i .

Let $S_i = (n-1)^{-1} \sum_{j=2}^{n} (X^i_{(j)} - X^i_{(1)})$. Now it is known that if sampling from $E(\mu_i, \sigma_i)$, that $X^i_{(1)}$ and S_i are independent (and sufficient for μ_i, σ_i). Further $n(X^i_{(1)} - \mu_i)/\sigma_i$ has the E(0,1) distribution and S_i is a $\gamma(n-1)/n-1$ variable.

For the case being considered, we have $\sigma_i = \sigma$, but σ is unknown. We will therefore use the pooled estimate

(3.13)
$$S = \frac{(n-1)S_1 + \cdots + (n-1)S_k}{k(n-1)} = \frac{1}{k} \sum_{i=1}^k S_i$$

and it is easy to see that S is a $\sigma\{\gamma(k(n-1))/k(n-1)\}$ variable.

Now, we wish to find the population with least $(\mu_i^{-a})/\sigma$, that is, with least μ_i . We assume, of course, that there is at least one population with $\mu_i < a$.

Let $t_i = nX_{(1)}^i$, and denote the ordered t's by

$$(3.14) t_{(1)} < t_{(2)} < \cdots < t_{(k)}.$$

We now adopt the following

Procedure. Retain Π_i if

$$(3.15) t_i < t_{(1)} + f_5 S$$

where f_5 is a constant chosen to make the $\Pr(CS) \ge P^*$. We now state the following

THEOREM 3.5: Procedure (3.15) is parameter-free.

PROOF: We have that the

$$\begin{aligned} \Pr(CS) &= \Pr(t_{(1)} \ge t - f_{5}S) \\ &= \Pr\left(\frac{t_{(1)} - n\mu_{[1]}}{S} \ge \frac{t - n\mu_{[1]}}{S} - f_{5}\right) \\ &= \Pr\left(U_{(1)}^{1} > U - f_{5}\right) \end{aligned}$$

where t is that t_i computed from the population having $\mu = \mu_{\Pi I}$,

U is a central U variable with k(n-1) degrees of freedom, and $U_{(1)}^{1}$ is a non-central U^{1} variable with k(n-1) degrees of freedom,

and non-centrality parameter

$$\delta_{[i]} = n \left(\frac{\mu_{[i]} - \mu_{[1]}}{\sigma} \right)$$

where $i \neq 1$. Hence the

$$\Pr(CS) = \int_0^\infty \left[\prod_{i=1}^k (1 - H(U - f_i; \delta_{[i]})) \right] dG(U)$$

where G(U) is the distribution function of (3.11) with v put equal to k(n-1), and $1-H(C; \delta)$ is given by (3.12). Now we have that 1-H is an increasing function in δ , and the Pr(CS) depends on a product of the (k-1) function, $1-H(U-f_{\delta}; \delta_{[i]})$, where

$$0 < \delta_{[2]} < \cdots < \delta_{[k]}$$
.

Therefore the $\Pr(CS)$ is minimized if $\delta_{[2]} = \cdots = \delta_{[k]} = 0$, and we have that the

$$\Pr(CS) \geq \int_0^\infty \left[\prod_{2}^k \left(1 - G(U - f_5) \right) \right] dG(U)$$

$$= \int_0^\infty \int_{u - f_5}^\infty \cdots \int_{u - f_5}^\infty \left[\prod_{1}^k \left(1 + \frac{U}{k(n-1)} \right)^{-[k(n-1)+1]} \right] dU_2 \cdots dU_k dU.$$

The last expression is a monotone increasing and continuous function of f_5 , and if we set it equal to P^* , there is a unique f_5 satisfying the resulting equation, and which is independent of the parameters. That is, (3.15) is parameter-free and such that the $Pr(CS) \ge P^*$.

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