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一般化レーマン対立仮説モデルと順位推定

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μ+ε

### α+βx+ε

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: 1. Model.

- : Generalized Lehmann's Alternative Model.
- : Semi parametric model. G(x)=h(F(x):θ) , G(x)=h(F(x-µ):θ) and G(x)=h(F(y-α-βx):θ)
- : Skew Symmetry . Azzalini (1985). Parametric model. MLE.

:2. Statistics.

- : Rank statistics for nonparametric Tests. Lehmann(1953).
- : Estimation. Miura (1985,1993)
- :3 . Asymptotic Normality.
  - : Special Construction (Skorokhod's Theorem, or Skorokhod's representation).
  - : Weak convergence of Empirical Distribution Functions.
  - : iid case and non-iid case( weakly dependent case.

This work is incomplete yet, but

: Make use of the results in Shao&Yu(1996). Louhichi(2000 and her other papers)).

:4. A direct application to a simple linear regression utilizes an weighted empirical distribution . Wellner&Shorack (1986). We need these for non-iid case.

# 1. Models

## Generalized Lehmann's Alternative Model. Generalize G(x)= F(x)<sup>θ</sup>, to G(x)=h(F(x):θ) Assume F(.) is symmetric about zero. Assume 関数形h(•:θ) is known, but F(.) unknown.

Definition. Let  $\Theta$  be an interval in the real line. A function  $h(t; \theta)$  for  $t \in (0, 1)$ and  $\theta \in \Theta$  which satisfies the following (1) and (2) is called the generalized Lehmann's alternative model;

(1)  $h(0;\theta) = 0$  and  $h(1;\theta) = 1$  for any  $\theta \in \Theta$ .  $h(t;\theta)$  is a strictly monotone function of t.

(2) There exists  $\theta^* \in \Theta$  such that  $h(t;\theta^*) = t$  for  $t \in (0,1)$ . And for  $\theta > \theta'$ ,  $h(t;\theta) < h(t;\theta')$  for all t (or < may be reversed for all t and  $\theta > \theta'$ ).

We shall also call  $h(F(\cdot); \theta)$  a generalized Lehmann's alternative model. In terms of random variables, the observations following a generalized Lehmann's

In the one-sample problem, it is not possible to estimate  $\theta$  for generalized Lehmann's alternative models  $h(F;\theta)$ , when F is unknown and no restrictions are made on the shape of F. The parameter  $\theta$  is not even identifiable in that case. Throughout this paper we assume:

$$F$$
 is continuous and  $F(x) = 1 - F(-x)$ . (1.1)

Also note that (2) in the definition of the generalized Lehmann's alternative model implies

$$h(t;\theta) + h(1-t;\theta) \neq 1 \text{ for } t \in (0,1) \text{ and } \theta \in \Theta - \{\theta^*\}.$$

$$(1.2)$$

Under (1.1) and (1.2),  $\theta$  is identifiable and can be estimated.

Examples. Let F and G be d.f.'s which are connected through the generalized Lehmann's alternative model  $G = h(F; \theta)$ . (i) If  $h(t; \theta) = 1 - (1 - t)^{\theta}$  for  $\theta \in (0, \infty)$ , then

$$\log \Lambda_G = \theta \log \Lambda_F,$$

where  $\Lambda_F$  and  $\Lambda_G$  are cumulative hazard functions corresponding to F and G respectively. This model is the well-known proportional hazards model proposed by Cox (1972).

(ii) Taking  $h(t;\theta) = t[(1-t)\theta + t]^{-1}$  for  $\theta \in (0,\infty)$  yields the proportional odds model:

$$\frac{G}{1-G} = \theta^{-1} \frac{F}{1-F}.$$

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This model has been considered by Ferguson (1967) and in more general regression setting by Pettitt (1984), among others.

The above two models have useful and important applications in survival analysis. Other examples of our model include Other examples of our model include

(iii)  $h(t;\theta) = (1-\theta)t + \theta t^2$  for  $\theta \in [0,1)$  (Contamination), (iv)  $h(t;\theta) = (e^{\theta t} - 1) / (\theta - 1) e^{\theta t} - \theta t^2$  for  $\theta \in [0,1)$  (Contamination),

$$\frac{(1v)}{(1v)} \frac{n(t;\theta)}{n(t;\theta)} = \frac{(e^{i\theta}-1)}{(e^{i\theta}-1)} \text{ for } \theta \in (0,\infty).$$

(iii) was considered in Lehmann (1953) and (iv) was found in Ferguson (1967). Both of these are Lehmann alternatives for which the locally most powerful rank test is Wilcoxon.

(v)  $h(t;\theta) = t^{\theta}$  for  $\theta \in (0,\infty)$  (Lehmann (1953)), (vi)  $h(t;\theta) = \sum_{i} c_{i}(\theta)t^{i}$  with  $\sum_{i} c_{i}(\theta) = 1$  and  $c_{i}(\theta) \geq 0$  for  $\theta \in \Theta$  (Mixture of extremals by a discrete distribution). (vii)  $h(t;\theta) = E(E^{-1}(t) - \log \theta)$  for  $\theta \in (0,\infty)$  where E is a known distribution function over the real line. This model can be rewritten as  $\psi(X) = \log \theta + \epsilon$  where  $X \sim G, \epsilon \sim E$  and  $\psi = E^{-1} \circ F$ , and includes (i) and (ii). See Dabrowska, Doksum and Miura (1989) for other examples and Tsukahara

(1991) for interesting relations among such models.

## (1).Transformation parameter θ, and (2). Simultaneous estimation of Transformation parameter θ and location parameter μ

: weakly dependent case (on going)

## Generalized Lehmann's Alternative model (GLAM) and skew symmetry:

### GLAM

 $G(x:\delta,F)=h(F(x):\delta). g(x:\delta,F)=h'(F(x):\delta)f(x)$ 

Skew symmetry (Azzalini)

 $g(x: \delta, F) = f(x)2F(\delta x), \text{ or } = f(x)2K(\delta x)$ 

Thus ,2F( $\delta x$ ) or f(x)2K( $\delta x$ ) in skew symmetry corresponds to h'(F(x):  $\delta$ ) in GLAM.

$$h(t:\delta,F,K) = \int_0^t 2K(\delta F^{-1}(u))du$$

and

$$h(F(x):\delta,F,K) = \int_0^{F(x)} 2K(\delta F^{-1}(u)) du$$





Fig.5-1 A rolling AR structure of a hedge fund's returns with Sharpe ratios

### 2. Statistics and Estimation for μ and θ in G(x)=h(F(x- μ): θ).

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#### ONE-SAMPLE ESTIMATION FOR GENERALIZED LEHMANN'S ALTERNATIVE MODELS

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Abstract: This paper shows that nonparametric estimation of  $\theta$  for generalized Lehmann's alternative models  $h(F;\theta)$  is possible, even in the one-sample problem, when symmetry of the basic distribution function F about zero, F(x) = 1 - F(-x), is assumed. Simultaneous nonparametric estimators of  $\mu$  and  $\theta$  for the model  $h(F(\cdot - \mu); \theta)$  are also provided under the symmetry of F. The asymptotic normality of these estimators is proved under certain regularity conditions.

# (1) Transformation Parameter θ

# (1). $X_1, ..., X_n$ distributed with G(x)=h(F(x): $\theta$ ). $X_i = \varepsilon_i$ , i=1,2,...,n.

In this section,  $X_1, X_2, \ldots, X_n$  are i.i.d. with d.f.  $G(x) = h(F(x); \theta_0)$  and  $\theta_0$  is to be estimated.

Let  $G_n(\cdot)$  be the empirical distribution function of  $X_i$ 's, that is,

$$G_n(x) \stackrel{\triangle}{=} n^{-1} \sum_{i=1}^n I_{[X_i \leq x]},$$

where  $I_A$  is an indicator function of a set A and let  $\tilde{G}_n(x)$  be a linearized version of  $G_n$ : let  $X_{(1)} < X_{(2)} < \cdots < X_{(n)}$  be the order statistics of  $X_i$ 's and define  $\tilde{G}_n(x)$  by

$$\tilde{G}_n(x) \stackrel{\triangle}{=} \frac{x + iX_{(i+1)} - (i+1)X_{(i)}}{(n+1)(X_{(i+1)} - X_{(i)})}, \quad x \in [X_{(i)}, X_{(i+1)}],$$

for i = 0, 1, ..., n with  $X_{(0)} = X_{(1)} - 1/n$  and  $X_{(n+1)} = X_{(n)} + 1/n$ . For i = 1, 2, ..., n, let  $Z_i(r) \stackrel{\Delta}{=} \tilde{G}_n^{-1}\left(h\left(\frac{i}{n+1}; r\right)\right)$ ,

and define

$$R_i^+(r) = \text{ the rank of } |Z_i(r)| \text{ among } \{|Z_j(r)| : j = 1, 2, ..., n\}.$$

Note that  $\tilde{G}_n^{-1}(h(\cdot;\theta_0))$  may be viewed as an estimator of  $F^{-1}$  and so  $Z_i(\theta_0)$ 's can be regarded as an approximation of the ordered sample from F. Also, by

$$egin{aligned} G_n(x) &\triangleq n^{-1} \sum_{i=1}^n I_{[X_i \leq x]}, & ilde{G}_n(x) &\triangleq rac{x + i X_{(i+1)} - (i+1) X_{(i)}}{(n+1) (X_{(i+1)} - X_{(i)})}, & x \in \left[X_{(i)}, X_{(i+1)}
ight] \ Z_i(r) &\triangleq ilde{G}_n^{-1} \left(h\left(rac{i}{n+1}; r
ight)
ight), & \int_0^1 J(t) dt = 0. \ R_i^+(r) &= ext{ the rank of } |Z_i(r)| ext{ among } \{|Z_j(r)|: j = 1, 2, \dots, n\}. \end{aligned}$$

$$S_n(r) \stackrel{\Delta}{=} \frac{1}{n} \sum_{i:Z_i(r)>0} J\left( \left( 1 + \frac{R_i^+(r)}{n+1} \right) / 2 \right) + \frac{1}{n} \sum_{i:Z_i(r)<0} J\left( \left( 1 - \frac{R_i^+(r)}{n+1} \right) / 2 \right). \quad (2.1)$$

Note that  $G(x)=(h(F(x):\theta)$ , so that  $G^{-1}(t)=F^{-1}(h^{-1}(t:\theta))$ , and  $G^{-1}(h(t:\theta))=F^{-1}(h^{-1}(h(t:\theta):\theta))=F^{-1}(t)$ . Thus,  $Z_i(\theta)$  is approximately distributed with F. We need to examine the probability distribution of Ranks in weakly dependent cases..

Monotonicity in r.

As r tends larger,  $Z_i(r)$  are shifted to larger, uniformly in i=1.2,...,n, and More of  $Z_i(r)$  will be positive.

This makes a similar shift to ranks of  $|Z_i(r)|$ .

 $S_n(r)$  as a function of r. It is larger for a large r.

Then the statistic we shall use for inference concerning  $\theta_0$  is

$$S_n(r) \stackrel{\triangle}{=} \frac{1}{n} \sum_{i:Z_i(r)>0} J\left( \left( 1 + \frac{R_i^+(r)}{n+1} \right) / 2 \right) + \frac{1}{n} \sum_{i:Z_i(r)<0} J\left( \left( 1 - \frac{R_i^+(r)}{n+1} \right) / 2 \right). \quad (2.1)$$

If J is symmetric about  $\frac{1}{2}$  in the sense that J(t) = -J(1-t),  $0 \le t < 1$ , then it is easy to see that

$$S_n(r) = rac{1}{n} \sum_{i=1}^n J^*\left(rac{R_i^+(r)}{n+1}
ight) \mathrm{sign} Z_i(r),$$

where  $J^*(t) = J((1+t)/2)$ ,  $0 \le t \le 1$ . So that the statistic  $S_n(r)$  may be regarded as a signed linear rank statistic. The point is that under (1.1) and (1.2)  $Z_1(r), Z_2(r), \ldots, Z_n(r)$  are thought of as a sample from a symmetric distribution only when  $r = \theta_0$ , and  $S_n(r)$  gives the strongest support to  $r = \theta_0$  when it is closest to zero. This makes it possible to estimate  $\theta$  even in the one-sample situation. Then our estimator  $\hat{\theta}_n$  of  $\theta_0$  is defined as the value of r which makes  $|S_n(r)|$  closest to zero. Such r exists since  $S_n(r)$  is nonincreasing in r. We can write

$$S_n(r) = \int_0^\infty J\left(\frac{1+H_{n,r}(x)}{2}\right) dL_{n,r}(x) + \int_{-\infty}^0 J\left(\frac{1-H_{n,r}(-x)}{2}\right) dL_{n,r}(x),$$

where

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$$egin{aligned} u_n(t)&\triangleq&rac{1}{n}igg( ext{the number of }igg\{i:rac{i}{n+1}\leq tigg\}igg),\ t\in(0,1),\ L_{n,r}(x)&\triangleq&rac{1}{n}igg( ext{the number of }igi\{i:Z_i(r)\leq xigg\}igg)\ &=&u_nigg(h^{-1}( ilde{G}_n(x);r)igg),\ x\in \mathbf{R},\ H_{n,r}(x)&\triangleq&rac{1}{n+1}igg( ext{the number of }igg\{i:|Z_i(r)|\leq xigg\}igg),\ x\in(0,\infty). \end{aligned}$$
 We set  $H(x) \triangleq F(x) - F(-x)$  for  $x\in(0,\infty).$ 

Next we shall state the assumptions which are necessary to prove the asymptotic normality of our estimator. Assume that  $h(t; \theta)$  is continuously differentiable with respect to t and  $\theta$  and let

$$h_1(t;\theta) \stackrel{\Delta}{=} \frac{\partial}{\partial t} h(t;\theta), \quad h_2(t;\theta) \stackrel{\Delta}{=} \frac{\partial}{\partial \theta} h(t;\theta).$$

Let u(t) = t(1-t). Assume, uniformly in  $\theta$  in a neighborhood of  $\theta_0$ ,

(A.1) 
$$|J'(t)| \le M \Big[ u(h(t;\theta_0)) \Big]^{-3/2+\delta}, \quad \text{for } \delta > 0$$

(A.2) 
$$\frac{1}{|h_1(t;\theta)|} \le M < \infty$$

(A.3) 
$$|h_2(t;\theta)| \le M \Big[ u(h(t;\theta_0)) \Big]^{1/2-\delta'}, \quad \text{for } \delta' > 0$$

where *M* is a universal constant. We require  $\rho \stackrel{\Delta}{=} \delta - \delta' > 0$ . Further, assume (A.4)  $h_k(t;\theta) \sim h_k(t;\theta_0)$  uniformly in  $t \in (0,1)$  as  $\theta \to \theta_0$ , (k=1,2). Assumptions (A.2)-(A.4) hold for Examples (i) and (v) with  $\theta_0 \leq 1$  and Examples (ii)-(iv). Note that (A.2) implies

$$\int_0^1 \left[ h(t;\theta)(1-h(t;\theta)) \right]^{-1+\rho} dt < \infty$$
(2.2)

by an easy change of variables. Also note that (A.1) and (A.2) imply

$$|J(t)| \le M \left[ u(h(t; \theta_0)) \right]^{-1/2+\delta};$$
 (2.3)

in fact, letting  $t_0$  be such that  $J(t_0) = 0$  and  $m \stackrel{\triangle}{=} h(t_0; \theta_0) > 0$ , we have

$$\begin{aligned} |J(t)| &= \left| \int_{t_0}^t J'(s) ds \right| &\leq M \int_{t_0}^t \left[ u(h(s;\theta_0)) \right]^{-3/2+\delta} ds \\ &\leq m^{-3/2+\delta} M \int_{t_0}^t \left( 1 - h(s;\theta_0) \right)^{-3/2+\delta} h_1(s;\theta_0) ds \\ &\leq M \left[ u(h(t;\theta_0)) \right]^{-1/2+\delta} \end{aligned}$$

for  $t > t_0$ , and it can be proven similarly for  $t < t_0$ .

For a function g on I (I = [0,1] or  $\mathbb{R}$ ), define  $||g|| = \sup_{t \in I} |g(t)|$ . By Skorohod's representation theorem, there exists a probability space on which a sequence of i.i.d. uniform (0,1) random variables  $U_{ni}$ 's and a Brownian bridge Uare defined and satisfy

$$||U_n - U|| \xrightarrow{\text{a.s.}} 0, \quad n \to \infty, \tag{2.4}$$

where

$$\Gamma_n(t) \stackrel{\Delta}{=} n^{-1} \sum_{i=1}^n I_{[U_{ni} \leq t]}, \quad t \in (0,1),$$
$$U_n(t) \stackrel{\Delta}{=} \sqrt{n} (\Gamma_n(t) - t), \quad t \in (0,1).$$

Using these  $U_{ni}$ 's, we shall represent the observation as  $X_i = G^{-1}(U_{ni})$  for i = 1, 2, ..., n, which is called the special construction following Shorack and Wellner (1986). We shall then obtain convergence in probability of the estimator, but on the original probability space we can claim convergence in distribution only.

$$S_n(r) = \int_0^\infty J\left(\frac{1+H_{n,r}(x)}{2}\right) dL_{n,r}(x) + \int_{-\infty}^0 J\left(\frac{1-H_{n,r}(-x)}{2}\right) dL_{n,r}(x),$$

where

$$egin{aligned} u_n(t) & & \triangleq \ rac{1}{n} igg( ext{the number of } \left\{ i: rac{i}{n+1} \leq t 
ight\} igg), \ t \in (0,1), \ L_{n,r}(x) & & \triangleq \ rac{1}{n} ig( ext{the number of } \left\{ i: Z_i(r) \leq x 
ight\} igg) \ & = \ u_n ig( h^{-1}( ilde{G}_n(x); r) igg), \ x \in \mathbf{R}, \ H_{n,r}(x) & & \triangleq \ rac{1}{n+1} ig( ext{the number of } \left\{ i: |Z_i(r)| \leq x 
ight\} igg), \ x \in (0,\infty). \end{aligned}$$

We set  $H(x) \stackrel{\triangle}{=} F(x) - F(-x)$  for  $x \in (0, \infty)$ . The following lemma is needed.

**Lemma 2.1.** Let  $r = \theta_0 + b/\sqrt{n}$ . Then for the special construction  $X_i = G^{-1}(U_{ni})$  and any given positive number B, we have, uniformly in x and  $|b| \leq B$ ,

$$\sqrt{n} \Big[ L_{n,r}(x) - F(x) \Big] \xrightarrow{\text{a.s.}} A(F(x)), \quad n \to \infty,$$
(2.5)

where

$$A(t) \stackrel{\triangle}{=} \frac{U(h(t;\theta_0))}{h_1(t;\theta_0)} - b \cdot \frac{h_2(t;\theta_0)}{h_1(t;\theta_0)},\tag{2.6}$$

provided (A.2)-(A.4) hold.

**Proof.** Let  $K_{n,r}(x) \stackrel{\Delta}{=} h^{-1}[\Gamma_n(G(x)); r]$ . We first prove that, uniformly in x and b,

$$\sqrt{n} \left| L_{n,r}(x) - K_{n,r}(x) \right| \xrightarrow{\text{a.s.}} 0 \tag{2.7}$$

as  $n \to \infty$ . This follows from

$$\sqrt{n} \Big[ K_{n,r}(x) - F(x) \Big] = \sqrt{n} \Big[ h^{-1}(\Gamma_n(G(x)); r) - h^{-1}(G(x); r) \Big] + \sqrt{n} \Big[ h^{-1}(G(x); r) - h^{-1}(G(x); \theta_0) \Big] \\
= \frac{U_n(G(x))}{h_1(h^{-1}(G^*(x); r); r)} - b \cdot \frac{h_2(h^{-1}(G(x); r^*); r^*)}{h_1(h^{-1}(G(x); r^*); r^*)}.$$
(2.8)

Theorem 2.1. Assume that  $h(t; \theta)$  is continuously differentiable with respect to t and  $\theta$  and  $\tau(\theta_0) > 0$ . Also let the assumptions (1.1), (A.1)-(A.4) hold. Then, as  $n \to \infty$ , we have

$$\sqrt{n} \left( \hat{\theta}_n - \theta_0 \right) \xrightarrow{d} N \left( 0, \frac{\sigma^2(\theta_0)}{\tau^2(\theta_0)} \right).$$

**Proof.** Noting that  $\int_0^1 J(t) dt = 0$ ,  $\sqrt{n}S_n(r)$  can be expressed as

$$\sqrt{n} \left[ \int_0^\infty J\left(\frac{1+H_{n,r}(x)}{2}\right) dL_{n,r}(x) - \int_0^\infty J\left(\frac{1+H(x)}{2}\right) dF(x) \right] + \sqrt{n} \left[ \int_{-\infty}^0 J\left(\frac{1-H_{n,r}(-x)}{2}\right) dL_{n,r}(x) - \int_{-\infty}^0 J\left(\frac{1-H(-x)}{2}\right) dF(x) \right]. (2.9)$$

Then the first term in (2.9) is decomposed to  $\sum_{i=1}^{2} B_{in} + \sum_{i=1}^{3} C_{in}$  where

$$B_{1n} \triangleq \int J\left(\frac{1+H}{2}\right) d\left\{\sqrt{n}(K_{n,r}-F)\right\},$$

$$B_{2n} \triangleq \frac{1}{2} \int \sqrt{n}(H_{n,r}-H) J'\left(\frac{1+H}{2}\right) dF,$$

$$C_{1n} \triangleq \int J\left(\frac{1+H_{n,r}}{2}\right) d\left\{\sqrt{n}(L_{n,r}-K_{n,r})\right\},$$

$$C_{2n} \triangleq \frac{1}{2} \int \sqrt{n}\left(H_{n,r}-H\right) J'\left(\frac{1+H}{2}\right) d\left(K_{n,r}-F\right),$$

$$C_{3n} \triangleq \sqrt{n} \int \left[J\left(\frac{1+H_{n,r}}{2}\right) - J\left(\frac{1+H}{2}\right) - \frac{1}{2}\left(H_{n,r}-H\right) J'\left(\frac{1+H}{2}\right)\right] dK_{n,r}.$$

Note that (1+H)/2 = F due to the symmetry of F, which we shall use repeatedly without mention.

to prove that  $\sqrt{n}[K_{n,r}(x) - F(x)]$  converges to the process on the right-hand side of (2.5). Now we have

$$\sqrt{n} \Big[ K_{n,r}(x) - F(x) \Big] \\
= \sqrt{n} \Big[ h^{-1}(\Gamma_n(G(x)); r) - h^{-1}(G(x); r) \Big] + \sqrt{n} \Big[ h^{-1}(G(x); r) - h^{-1}(G(x); \theta_0) \Big] \\
= \frac{U_n(G(x))}{h_1(h^{-1}(G^*(x); r); r)} - b \cdot \frac{h_2(h^{-1}(G(x); r^*); r^*)}{h_1(h^{-1}(G(x); r^*); r^*)}.$$
(2.8)

Here  $G^*(x)$  is a random function taking values between G(x) and  $\Gamma_n(G(x))$ , and  $r^*$  lies between  $\theta_0$  and r. Then

$$\begin{split} & \left\| \frac{U_n(G(x))}{h_1(h^{-1}(G^*(x);r);r)} - \frac{U(G(x))}{h_1(F(x);\theta_0)} \right\| \\ & \leq \|M\| \frac{h_1(F(x);\theta_0)}{h_1(h^{-1}(G^*(x);r);r)} - 1\| \cdot \|U_n(G(x))\| + M\|U_n(G(x)) - U(G(x))\|. \end{split}$$

It follows from Glivenko-Cantelli theorem that  $||G^*(x) - G(x)|| \xrightarrow{\text{a.s.}} 0$ . Also  $r^* \to \theta_0$  uniformly in b as  $n \to \infty$ . Thus the first term converges almost surely to 0 by virtue of (A.4) and  $||U_n(G(x))|| \xrightarrow{\text{a.s.}} O(1)$ , which is an easy consequence of (2.4). Next by (2.4) and (A.2), we see that the second term converges almost surely to 0. Furthermore it follows from (A.2)-(A.4) that

$$\left\|\frac{h_2(h^{-1}(G(x);r^*);r^*)}{h_1(h^{-1}(G(x);r^*);r^*)}-\frac{h_2(F(x);\theta_0)}{h_1(F(x);\theta_0)}\right\| \longrightarrow 0.$$

Therefore (2.8) converges almost surely to

$$\frac{U(G(x))}{h_1(F(x);\theta_0)}-b\cdot\frac{h_2(F(x);\theta_0)}{h_1(F(x);\theta_0)},$$

uniformly in x and b, which completes the proof of the lemma.

Thus

$$\sum_{i=1}^{2} B_{in} \xrightarrow{P} -\frac{1}{2} \int_{\frac{1}{2}}^{1} \left[ \frac{U(h(t;\theta_{0}))}{h_{1}(t;\theta_{0})} + \frac{U(h(1-t;\theta_{0}))}{h_{1}(1-t;\theta_{0})} \right] dJ(t) \\ + \frac{b}{2} \int_{\frac{1}{2}}^{1} \left[ \frac{h_{2}(t;\theta_{0})}{h_{1}(t;\theta_{0})} + \frac{h_{2}(1-t;\theta_{0})}{h_{1}(1-t;\theta_{0})} \right] dJ(t) + \lambda(1/2). \quad (2.13)$$

Next we show that  $\sum_{i=1}^{3} C_{in} \xrightarrow{P} 0$ . For  $C_{1n}$ , note that  $H_{n,r} \leq n/(n+1)$ .

It can be seen in the similar way that the second term in (2.9) converges in probability to

$$-\frac{1}{2}\int_{0}^{\frac{1}{2}}\left[\frac{U(h(t;\theta_{0}))}{h_{1}(t;\theta_{0})}+\frac{U(h(1-t;\theta_{0}))}{h_{1}(1-t;\theta_{0})}\right]dJ(t) \\ +\frac{b}{2}\int_{0}^{\frac{1}{2}}\left[\frac{h_{2}(t;\theta_{0})}{h_{1}(t;\theta_{0})}+\frac{h_{2}(1-t;\theta_{0})}{h_{1}(1-t;\theta_{0})}\right]dJ(t)-\lambda(1/2).$$

we obtain asymptotic linearity: for any B > 0

$$\sup_{|b| \le B} \left| \sqrt{n} S_n(r) + \frac{1}{2} T - \frac{1}{2} b \tau(\theta_0) \right| \xrightarrow{P} 0, \qquad (2.14)$$

where

$$T \triangleq \int_0^1 \left[ \frac{U(h(t;\theta_0))}{h_1(t;\theta_0)} + \frac{U(h(1-t;\theta_0))}{h_1(1-t;\theta_0)} \right] dJ(t).$$

Now let  $\epsilon > 0$  be a given number small enough to satisfy  $\epsilon < \tau(\theta_0)/2$ . Take  $B_{\epsilon} > 1$  so large that

$$P\left\{|T| > \frac{B_{\epsilon}\tau(\theta_0)}{2}\right\} < \frac{\epsilon}{2}.$$

By asymptotic linearity (2.14), there exists an  $N_{\epsilon}$  such that for all  $n \geq N_{\epsilon}$ ,

$$P\left\{\sup_{|b|\leq B_{\epsilon}}\left|\sqrt{n}S_{n}(r)+\frac{1}{2}T-\frac{b}{2}\tau(\theta_{0})\right|>\epsilon\right\}<\frac{\epsilon}{2}.$$

Thus for all  $n \ge N_{\epsilon}$ , any value  $b_n$  of b which minimizes  $|\sqrt{n}S_n(r)| = |\sqrt{n}S_n(\theta_0 + b/\sqrt{n})|$  lies in  $[-B_{\epsilon}, B_{\epsilon}]$  and it follows that

$$|b_n - T/\tau(\theta_0)| < \epsilon/\tau(\theta_0)$$

with probability exceeding  $1-\epsilon$  (note that  $T/\tau(\theta_0)$  minimizes  $|-T/2+b\tau(\theta_0)/2|$ ). Noting that  $\sqrt{n}(\hat{\theta}_n - \theta_0)$  is a value of b which minimizes  $|\sqrt{n}S_n(r)|$ , we obtain

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{P} \frac{T}{\tau(\theta_0)}$$

## iid から weakly dependent へ stationary process : strongly mixing or associated

For a function g on I (I = [0,1] or  $\mathbb{R}$ ), define  $||g|| = \sup_{t \in I} |g(t)|$ . By Skorohod's representation theorem, there exists a probability space on which a sequence of i.i.d. uniform (0,1) random variables  $U_{ni}$ 's and a Brownian bridge Uare defined and satisfy

$$||U_n - U|| \xrightarrow{\text{a.s.}} 0, \quad n \to \infty, \tag{2.4}$$

where

$$\Gamma_n(t) \stackrel{\Delta}{=} n^{-1} \sum_{i=1}^n I_{[U_{ni} \le t]}, \quad t \in (0,1),$$
$$U_n(t) \stackrel{\Delta}{=} \sqrt{n} (\Gamma_n(t) - t), \quad t \in (0,1).$$

#### WEAK CONVERGENCE FOR WEIGHTED EMPIRICAL PROCESSES OF DEPENDENT SEQUENCES

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While the problem of weak convergence for weighted empirical processes of independent sequences has been intensively studied in recent years, there are only a few studies concerned with the counterpart for dependent sequences [cf. Yu (1993a)]. In the latter case the limit process is changed from being a Brownian bridge due to the appearance of covariances among observations. Namely, under certain conditions, we have

(1.7) 
$$\alpha_n(\cdot) \to_{\mathscr{D}} B^*(\cdot) \text{ in } D[0,1],$$

where  $B^*(\cdot)$  is a zero-mean Gaussian process specified by  $B^*(0) = B^*(1) = 1$ and

$$EB^*(s)B^*(t) = s \wedge t - st$$

$$+ \sum_{k=2}^{\infty} \left\{ Cov(I(U_1 \le s), I(U_k \le t)) + Cov(I(U_k \le s), I(U_1 \le t)) \right\}$$

## iid case

Also Pyke and Shorack (1968) show that  $||(U_n(t) - U(t))/q(t)|| \xrightarrow{P} 0$  for  $q(t) = [u(t)]^{1/2-\delta}$  for some  $\delta > 0$ . Note that this implies

### Non-iid case (weakly dependent): $\alpha$ -mixing or associated.

**Proposition 2.2 (Shao and Yu)** Suppose that  $(\xi_n)_{n \in \mathbb{N}}$  is a strictly stationary sequence of U(0,1) random variables which is also strongly mixing with the mixing rate

$$\alpha(n) = O(n^{-\theta - \eta})$$
 for some  $\theta \ge 1 + \sqrt{2}$ , and  $\eta > 0$ .

Then  $\mathbb{U}_n/q \xrightarrow{\mathcal{L}} \mathbb{U}/q$  in D[0,1], where  $q(u) := [u(1-u)]^{1/2-1/(2\theta)}$  and  $\mathbb{U}$  is a Gaussian process with  $\mathbb{U}(0) = \mathbb{U}(1) = 0$  and

$$E[\mathbb{U}(u)] = 0, \quad E[\mathbb{U}(u)\mathbb{U}(v)] = \sigma(u, v).$$

$$\alpha(n) = \sup_{k \ge 1} \alpha(\mathscr{F}_1^k, \mathscr{F}_{n+k}^\infty). \qquad \mathscr{F}_n^m = \sigma(X_i, n \le i \le m)$$
  
$$1 + \sqrt{2} \le \theta$$
  
$$2(1 + \sqrt{2}) \le 2\theta, \implies 0 < \frac{1}{2\theta} \le \frac{1}{2(1 + \sqrt{2})} = 0.208.....$$

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### Weak convergence for empirical processes of associated sequences

by

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#### 2. MAIN RESULT AND APPLICATION

THEOREM 1. – Let  $(X_n)_{n \in \mathbb{Z}}$  be a stationary associated sequence with continuous marginal distribution F. Assume that, for  $n \in \mathbb{N}^*$ ,

$$\operatorname{Cov}(F(X_1), F(X_n)) = \mathcal{O}(n^{-b}), \quad \text{for } b > 4.$$
(10)

Then

 $G_n(.) \to G(.)$  in  $D[-\infty, +\infty]$ ,

This argument in the weak dependent case goes very similar (almost the same) as in the case of iid.

The only difference would be

- (1) assumptions on the power, and
- (2) asymptotic variance.

(3) Need to examine the probability distribution of rank vectors if it is well asymptotically uniform over (0,1),or distributed to satisfy that sum of rank score to be zero:

$$S_n(r) \stackrel{\triangle}{=} \frac{1}{n} \sum_{i:Z_i(r)>0} J\left( \left( 1 + \frac{R_i^+(r)}{n+1} \right) / 2 \right) + \frac{1}{n} \sum_{i:Z_i(r)<0} J\left( \left( 1 - \frac{R_i^+(r)}{n+1} \right) / 2 \right). \quad (2.1)$$

# (2). $\theta$ and $\mu$ . Simultaneously.

(2).  $X_1, ..., X_n$  distributed with  $G(x)=h(F(x-\mu): \theta)$ .  $X_i = \mu + \epsilon_i$ , i=1,2,...,n.  $\epsilon_i$  follows  $G(x)=h(F(x): \theta)$ 

 $S_{1,n}$  (r, q) and  $S_{2,n}$  (r, q)

$$G_n(\mathbf{x}) \stackrel{\triangle}{=} n^{-1} \sum_{i=1}^n I_{[X_i \leq \mathbf{x}]},$$

$$\begin{split} \tilde{G}_n(x) &\triangleq \frac{x + iX_{(i+1)} - (i+1)X_{(i)}}{(n+1)(X_{(i+1)} - X_{(i)})}, \quad x \in \left[X_{(i)}, X_{(i+1)}\right] \\ Z_i(r) &\triangleq \tilde{G}_n^{-1}\left(h\left(\frac{i}{n+1}; r\right)\right), \quad Z_i(r) \text{ are approximately distributed arround } \mu \text{ with } \mathsf{F}(\bullet - \mu). \end{split}$$

.

#### **3.** Simultaneous Estimation of $\mu$ and $\theta$

In this section, let  $X_1, X_2, \ldots, X_n$  be i.i.d. with d.f.  $G(x) = h(F(x - \mu_0); \theta_0)$ . The parameters  $\mu_0$  and  $\theta_0$  are both unknown and are to be estimated simultaneously.

Let  $Z_i(r)$  be as in Section 2 and define

$$R_i^+(r,q) = \Big( ext{the number of } \{j: |Z_j(r)-q| \leq |Z_i(r)-q|\}\Big).$$

Note. For a value of r close to the true parameter value,

 $Z_i(r), i = 1, 2, ..., n$  are approximately symmetrically distributed arround zero. Hence this q is a generalization of Hodge Lehmann estimate of center of symmetry. (H-L from a linear score function.) In this section assume that F has a bounded continuous density f. Let  $J_1(\cdot)$  and  $J_2(\cdot)$  be the score function used for estimation of  $\theta$  and  $\mu$  respectively.  $J_1(\cdot)$  and  $J_2(\cdot)$  satisfy the conditions for the score functions in Section 2. In addition,  $J_1(\cdot)$  and  $J_2(\cdot)$  are assumed different enough to satisfy

$$\frac{\int_{0}^{1} \left[ \frac{h_{2}(t;\theta_{0})}{h_{1}(t;\theta_{0})} + \frac{h_{2}(1-t;\theta_{0})}{h_{1}(1-t;\theta_{0})} \right] dJ_{1}(t)}{\int_{0}^{1} \left[ \frac{h_{2}(t;\theta_{0})}{h_{1}(t;\theta_{0})} + \frac{h_{2}(1-t;\theta_{0})}{h_{1}(1-t;\theta_{0})} \right] dJ_{2}(t)} \neq \frac{\int_{0}^{1} f(F^{-1}(t)) dJ_{1}(t)}{\int_{0}^{1} f(F^{-1}(t)) dJ_{2}(t)}.$$
(3.1)

The rank statistics for the simultaneous inference of  $\mu$  and  $\theta$  are defined as follows:

$$S_{1n}(r,q) \triangleq \frac{1}{n} \sum_{i:Z_i(r)>q} J_1\left(\left(1 + \frac{R_i^+(r,q)}{n+1}\right)/2\right) + \frac{1}{n} \sum_{i:Z_i(r)\leq q} J_1\left(\left(1 - \frac{R_i^+(r,q)}{n+1}\right)/2\right),$$
(3.2)

and

$$S_{2n}(r,q) \stackrel{\triangle}{=} \frac{1}{n} \sum_{i:Z_i(r)>q} J_2\left(\left(1 + \frac{R_i^+(r,q)}{n+1}\right)/2\right) + \frac{1}{n} \sum_{i:Z_i(r)\leq q} J_2\left(\left(1 - \frac{R_i^+(r,q)}{n+1}\right)/2\right).$$
(3.3)

Our estimators of  $\mu$  and  $\theta$  are derived from the simultaneous equations  $S_{1n}(r,q) \approx 0$  and  $S_{2n}(r,q) \approx 0$ . Define

$$D_n \stackrel{ riangle}{=} \left\{ (r,q) : \sum_{k=1}^2 |S_{kn}(r,q)| = \min \right\}.$$

 $D_n \subset \Theta \times \mathbf{R}$  is not empty for all  $X_1, X_2, \ldots, X_n$  since  $S_{kn}(r,q)$ , as a function of r and q with fixed  $X_1, X_2, \ldots, X_n$ , takes on a finite number of different values.  $S_{kn}(r,q), (k=1,2)$  are nonincreasing in each coordinate r and q separately, but it does not ensure the convexity of  $D_n$ , which may be used to determine the estimators uniquely. Our estimator  $(\hat{\theta}_n, \hat{\mu}_n)$  is thus defined to be any point of  $D_n$ . Since  $(\hat{\theta}_n, \hat{\mu}_n)$  may not be unique, there may be some arbitrariness in this definition. But, as will turn out in Theorem 3.2 below, all points in  $D_n$  are asymptotically equivalent; so, for large n, it will not matter much how  $(\hat{\theta}_n, \hat{\mu}_n)$  chosen.

To investigate the asymptotic behavior of  $S_{kn}$ , we assume, in addition to (A.1) with J replaced by  $J_k$  and (A.2)-(A.4),

(A.5) 
$$|J'_{k}(t)| \leq M[u(t)]^{-1+\delta}, \ \delta > 0.$$

We also introduce the following notation: let  $r = \theta_0 + b_1/\sqrt{n}$ ,  $q = \mu_0 + b_2/\sqrt{n}$ and

$$\boldsymbol{S}_{\boldsymbol{n}}(r,q) \stackrel{\Delta}{=} \left( S_{1\boldsymbol{n}}(r,q), S_{2\boldsymbol{n}}(r,q) \right)', \quad \boldsymbol{b} \stackrel{\Delta}{=} (b_1,b_2)'.$$

Furthermore, for k = 1, 2

$$T_k \stackrel{\triangle}{=} \int_0^1 \left\{ \frac{U(h(t;\theta_0))}{h_1(t;\theta_0)} + \frac{U(h(1-t;\theta_0))}{h_1(1-t;\theta_0)} \right\} dJ_k(t),$$

and set  $T \stackrel{\triangle}{=} (T_1, T_2)'$ . Let  $D = [d_{kl}]$  denote a 2 × 2 matrix, where

$$d_{k1} \stackrel{\triangle}{=} \int_0^1 \left\{ \frac{h_2(t;\theta_0)}{h_1(t;\theta_0)} + \frac{h_2(1-t;\theta_0)}{h_1(1-t;\theta_0)} \right\} dJ_k(t),$$
  
$$d_{k2} \stackrel{\triangle}{=} -2 \int_0^1 f(F^{-1}(t)) dJ_k(t) \quad (k=1,2).$$

Note that D is nonsingular because of (3.1). Then we have the following asymptotic linearity result.

**Theorem 3.1.** Suppose that F has a bounded continuous density f and that (A.1) with J replaced by  $J_k$  and (A.2)-(A.5) all hold. Then

$$\max_{k=1,2} \sup_{|b_k| \le B} \left| \sqrt{n} S_{kn}(r,q) + \frac{1}{2} T_k - \frac{1}{2} (d_{k1} b_1 + d_{k2} b_2) \right| \xrightarrow{P} 0, \quad n \to \infty, \quad (3.4)$$

for each  $0 < B < \infty$ .

Using matrix notation, express the relation (3.4) as

$$\sup_{|\boldsymbol{b}_{\boldsymbol{k}}| \leq B} \left| \sqrt{n} \boldsymbol{S}_{\boldsymbol{n}}(\boldsymbol{r}, \boldsymbol{q}) + \frac{1}{2} \boldsymbol{T} - \frac{1}{2} D \boldsymbol{b} \right| \xrightarrow{P} \boldsymbol{0}, \quad \boldsymbol{n} \to \infty.$$
(3.5)

**Theorem 3.2.** Suppose that all the conditions of Theorem 3.1 are satisfied. Then each point of  $D_n$  is asymptotically normal  $N(0, D^{-1}\Sigma(D^{-1})')$ , that is,

$$\sqrt{n} \left( \begin{array}{c} \hat{\theta}_n - \theta_0 \\ \hat{\mu}_n - \mu_0 \end{array} \right) \xrightarrow{d} N \left( 0, D^{-1} \Sigma (D^{-1})' \right),$$

as  $n \to \infty$ .

A Simple Linear Regression Model. (On-going trial)

Y=α+βx+ε. Where ε≈ G(.)=h(F(.):θ) F(.) symmetric around zero.

$$Y_i = \alpha + \beta x_i + \varepsilon_i$$
,  $i = 1, 2, ..., n$ 

ε<sub>i</sub> ,i=1,2,...,n :weakly dependent(associated),

## And distributed with G(.)=h(F(.):θ)

注意:最小二乗法との違い。

順位統計量から導かれる回帰係数βの推定は、回帰モデルの偶然誤差 項が対称性を持つことなど分布形の仮定を置かない。また、αの推定は 、βを推定した後に行う。





#### 順位統計量にもとづくベータの推定:日本の株価データについて:補遺(三浦)



### Motivations.

## Data in Financial Engineering: Time series data of Hedge Fund return .

: In a usual regression where returns of portfolios or of stocks are regressed on indices (stock index, for example), the residuals are rather implicitly regarded as iid. They may be almost so, but they may not be so.

In practice, they do not care about estimation error? (In econometrics, or in academics, they surely care about it.)

: When hedge fund returns are regressed on market indices as in the following, the residuals do not seem iid, but may show some dependence, such as autoregressive.

: This kind of regression is often done in a search for possibilities of Hedge fund replication.

## Estimate $\beta$ , $\theta$ and $\alpha$ simultaneously. $S_{1,n}$ (b, r) for $\beta$ , or $S_{1,n}$ (b) $S_{2,n}$ (b, r, a) for $\theta$ , and $S_{3,n}$ (b, r, a) for $\alpha$ .

## Mathematics.

 use the convergence of weighted empirical distribution functions, {Y- βx} empirical distribution function that is described in Wellner & Shorack(1986) and others.

(2) follow Hajek& Sidak(1967) and Jureckova (1971) with Jaeckel (1972), Also Sen& Jureckova(199?) and Wellner &Shorack (1986) with Shao&Yu (1996) and Louhichi(2000), in order to prove asymptotic normality of linear rank statistics in our weakly dependent case. We are on the way to prove fundamental theorems for distributions for rank vectors. Can we do the same for a regression model as for a location only ? Can we base everything on symmetry of F with empirical distribution functions ?

Let 
$$e_i(\beta) = Y_i - \beta x_i$$
, i=1,2,..., n.  
(1).Note that  $e_i(\beta)$  is distributed with  $G(x-\alpha)=h(F(x-\alpha):\theta_0)$ .  
(2).Note also that  $E[e_i(\beta)] = \alpha + \int_{-\infty}^{\infty} x dh(F(x):\theta_0)$   
 $= \alpha + \int_0^1 F^{-1}(t) dh(t;\theta_0)$   
 $= \alpha + m(\theta_0)$ 

where the second term  $m(\theta_0)$  is non-zero unless  $\theta_0 = \theta^*$ .

(3).Note that one can estimate  $\beta$  based on rank statistics with ranks of  $e_i(b), i = 1, 2, ..., n$  without simultaneously estimate  $\alpha$  and  $\theta_0$ . This is an important feature of rank statistics in linear regression models and estimates derived from rank statistics. Here, we will estimate  $\alpha$  and  $\theta_0$ .

Let 
$$E_n(x : b) = \frac{1}{n+1} \sum_{i=1}^n I\{e_i(b) \le x\}.$$

Let  $E_n(.)$  be a piecewise linear version of  $E_n(.)$ .

(4).Note that  $E^{-1}(t) = \alpha + F^{-1}(h^{-1}(t;\theta_0))$  or  $E^{-1}(U) \triangleq \alpha + F^{-1}(h^{-1}(U;\theta_0))$ and that

 $E^{-1}(h(t;\theta_0)) = \alpha + F^{-1}(t)$  and

 $E^{-1}(h(U;\theta_0))$  has a distribution  $F(x-\alpha)$ ,

for E(x)=P{ $e_i(\beta) < x$ } and an uniform random variable U on [0,1].

Now, let 
$$Z_i(b, r) = \widetilde{E_n^{-1}(h(\frac{i}{n+1}:r))}$$
,  $i=1,2,...,n$ .

Then, these are expected to distribute symmetrically arround  $\alpha$ ; approximately with F(x- $\alpha$ ).

(5).Note that expectation 
$$E[U_{(i)}] = \frac{i}{n+1}$$
 and  $U_{(i)} - \frac{i}{n+1}$  converges to zero.  
(6).Note that  $m(\theta)$  can be estimated by  $\widehat{m(\theta)}$ .

and let  $R_i(b, r) = rank$  of  $Z_i(b, r)$  among  $\{Z_j(b, r), j=1,2,...,n\}$   $= \sum_{j=1}^{n} I\{Z_j(b, r) \le Z_i(b, r)\}.$ let  $R_i^+(b, r, a) = rank$  of  $|Z_i(b, r) - a|$  among  $\{|Z_j(b, r) - a|, j=1,2,...,n\}$  $= \sum_{j=1}^{n} I\{|Z_j(b, r) - a| \le |Z_i(b, r) - a|\}.$   $(\beta, \theta, \alpha) \leftarrow (b, r, a)$ 

 $\beta: S_{1,n}(b,r) = \frac{1}{n} \sum_{i=1}^{n} J_1(R_i(b,r))(x_i - x)$ 

(7).Note that this kind of rank statistics was given

in Jureckova(1969,1971 and others) and Jaeckel(1972).

(8).Note also that there is another choice of using this without r.

$$\theta: S_{2,n}(\mathbf{b},\mathbf{r},\mathbf{a}) = \frac{1}{n} \sum_{i: \ zi(\mathbf{b},\mathbf{r})>a} J_2(\frac{1}{2} + \frac{R_i^+(\mathbf{b},\mathbf{r},\mathbf{a})}{2}) + \frac{1}{n} \sum_{i: \ zi(\mathbf{b},\mathbf{r})\leq a} J_2(\frac{1}{2} + \frac{R_i^+(\mathbf{b},\mathbf{r},\mathbf{a})}{2})$$
  
$$\alpha: S_{1,n}(\mathbf{b},\mathbf{r},\mathbf{a}) = \frac{1}{n} \sum_{i: \ zi(\mathbf{b},\mathbf{r})>a} J_3(\frac{1}{2} + \frac{R_i^+(\mathbf{b},\mathbf{r},\mathbf{a})}{2}) + \frac{1}{n} \sum_{i: \ zi(\mathbf{b},\mathbf{r})\leq a} J_3(\frac{1}{2} + \frac{R_i^+(\mathbf{b},\mathbf{r},\mathbf{a})}{2})$$

(9).Note that these two rank statistics are similarly defined to Tsukahara and Miura(1993); i.e. a version for a simple linear regression model.

### i.i.d. case.

Jureckova (1971,1969) and Jaeckel (1972). Hajek & Sidak [Theory of Rank Test] 1967. Estimation of β based on rank statistics, where the distribution of ε can be asymmetric.

Note that  $\beta$  can be estimated separately from  $\mu$  and  $\theta$ . We take advantage of this nature .

### Plan of a proof.

One can use their result for estimation for  $\beta$ .

Then, in order to estimate  $\mu$  and  $\theta$ , one may use the estimated  $\beta$  in  $Y_i - \beta x_i$ , and work on empirical distribution function with the above  $X_i$  replaced by  $Y_i - \beta x_i$ , where estimated  $\beta$  converges to a true  $\beta$ .

Note that for iid case this can be done by conbining the results in the Jureckova(1971) and Tsukahara&Miura(1993). It will be a new result.

### Dispersion measure $D(Y-\beta x)$ .

### Estimator $\beta$ ; minimizes D.

### similar to LSE, but different in replacing (...) with ranks.

D' is a non-decreasing step function of  $\beta$ ; Steps at (Y.- Y.)/(x.-x.) . 1 < i<i < n.

Note that ranks are shift-invariant, so that intercept  $\alpha$  or  $\mu$  does not matter in D'.

$$D(Y - \beta C) = \sum a_N(k)(Y_{i(k)} - \beta c^{i(k)}),$$
$$D'(Y - \beta C) = \frac{dD}{d\beta} = -\sum a_N(k)c^{i(k)}$$

For fixed  $Y_1, Y_2, \dots, Y_N$  and for any  $\beta$ , the residuals are

(2.2) 
$$z_i = Y_i - \beta c^i$$
  $i = 1, 2, \dots, N$ 

The ordered residuals are

$$z_{(k)} = Y_{i(k)} - \beta c^{i(k)}$$
  $k = 1, 2, \dots, N$ ,

where i(k) is the index of the observation giving rise to the kth ordered residual. (If two residuals are equal there is an ambiguity in i(k) but not in  $z_{(k)}$ .) The

## Non iid, weakly dependent cases.

Proceed in the same way as in iid case.

Numerical calculations for the estimates of  $\beta$  is the same as in iid case.

But, the probability distribution of the estimator or the estimation error are different in the two cases.

Approaches for proving asymptotic normality.

: (1). Approach in Jureckova and Jaeckel. This does not look using a convergence of weighted empirical distribution function (in iid case).

: (2). Can we use "a convergence of weighted empirical distribution function " framework for this problem?

Y<sub>i</sub>-βx<sub>i</sub>, i=1,2,...,n. Yes, we can. See Wellner & Shorack(1986) for iid cases.

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# Thank you for your attention.